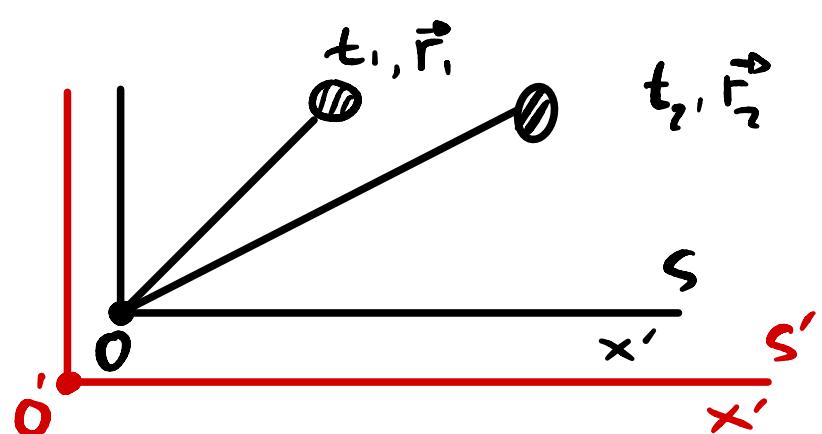


Συστηματικά αναφορές



π.χ.

Κλασικό δυναμικό αντιτειλόμερος

$$U(r_1, r_2) = -\frac{GM \cdot m_2}{|\vec{r}_2 - \vec{r}_1|}$$

$$\vec{F}_{2,1} = -\frac{GM \cdot m_2}{|\vec{r}_2 - \vec{r}_1|^3} (\vec{r}_2 - \vec{r}_1)$$

(υποθέτει ανειρονομική ταχύτητα αντιτειλόμερων)

Αδρανείκα συστηματικά αναφορές

Όταν $\vec{F}_{ext} = 0$ τότε $\frac{d\vec{r}}{dt} = \text{const}$

Υπάρχουν αρείρα ΑΣΑ: οι εξισώσεις κινήσεων δεν πρέπει να εξαρτάνται από την επιλογή του ΑΣΑ

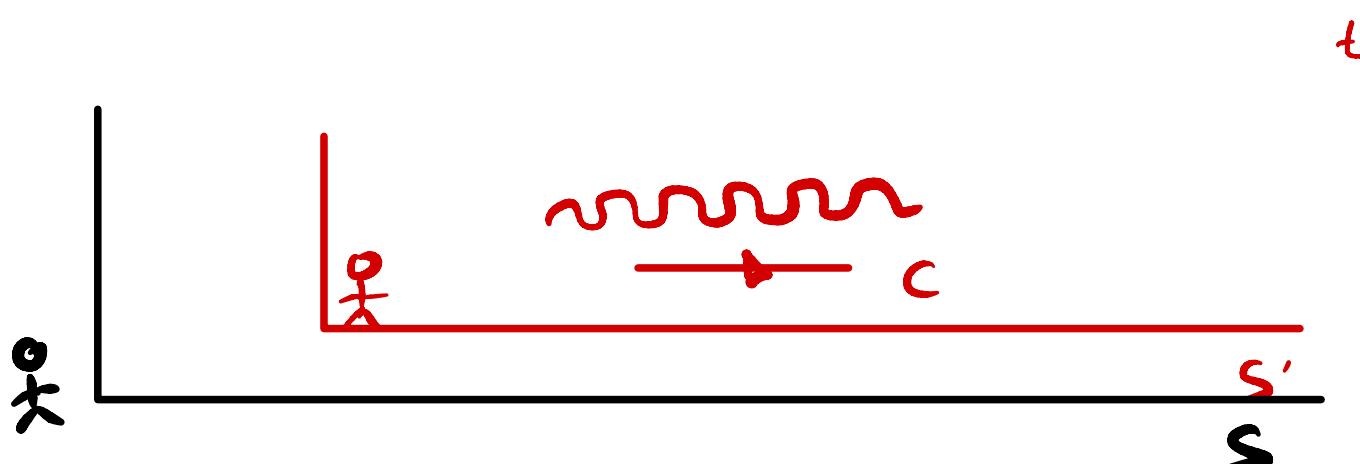
Αξιωματικές σχέσεις → Ιδεαλισμός ΑΣΑ

Περιφραγμένα γιατίσουμε ότι υπάρχει συναλλαγή ανά μήκος, μερική ταχύτητα αντιτειλόμερη, $c = 3 \cdot 10^8 \text{ m/s}$

- Ιδία για όλα τα ΑΣΑ (αξιωματικές σχέσεις)
- Κανένα σώμα δε μπορεί να ταξιδεύει με όργανα από αυτή

$$\{f, g, G(\cdot)\}$$

$$\begin{aligned} m &= 0 \\ q &= 0 \end{aligned}$$



TAVVUTES

$$dx^{\mu'} = \frac{\partial x^{\mu'}}{\partial x^\mu} dx^\mu \stackrel{(L.T.)}{=} \Lambda_{\mu}^{\mu'} dx^{\mu'}$$

↑ αντιροπτό διανυγμα μετατοπίσης
 $(A^{\mu'} = \frac{\partial x^{\mu'}}{\partial x^\mu} A^\mu)$

ευνήσιμος ταυτότητας \perp^{eq} ταξεως

$$\partial_\mu \equiv \frac{\partial}{\partial x^\mu} = \frac{\partial x^{\mu'}}{\partial x^\mu} \frac{\partial}{\partial x^{\mu'}}$$

$$dx_{\mu'} = \frac{\partial x_\mu}{\partial x^{\mu'}} dx_\mu = \Lambda_{\mu'}{}^\mu dx_\mu$$

αυτονομίας
 ταυτότητας \perp^{eq}
 ταξεως
 contravariant

$$A^\mu = (A^0, A^1, A^2, A^3)$$

$$A_\mu = (-A^0, A^1, A^2, A^3)$$

$$A_\mu = (A_0, A_1, A_2, A_3)$$

$$\begin{pmatrix} A_0 = -A^0 \\ A_i = A^i \end{pmatrix}$$

$$\begin{pmatrix} dx^0 \\ dx^1 \\ dx^2 \\ dx^3 \end{pmatrix} = \begin{bmatrix} \frac{\partial x^0'}{\partial x^0} & \frac{\partial x^0'}{\partial x^1} & \frac{\partial x^0'}{\partial x^2} & \frac{\partial x^0'}{\partial x^3} \\ \frac{\partial x^1'}{\partial x^0} & \frac{\partial x^1'}{\partial x^1} & \frac{\partial x^1'}{\partial x^2} & \frac{\partial x^1'}{\partial x^3} \\ \frac{\partial x^2'}{\partial x^0} & \frac{\partial x^2'}{\partial x^1} & \frac{\partial x^2'}{\partial x^2} & \frac{\partial x^2'}{\partial x^3} \\ \frac{\partial x^3'}{\partial x^0} & \frac{\partial x^3'}{\partial x^1} & \frac{\partial x^3'}{\partial x^2} & \frac{\partial x^3'}{\partial x^3} \end{bmatrix} \begin{pmatrix} dx^0 \\ dx^1 \\ dx^2 \\ dx^3 \end{pmatrix}$$

$$\begin{pmatrix} dx^0 \\ dx^1 \\ dx^2 \\ dx^3 \end{pmatrix}$$

Jacobian

$$\text{n.x. για ρυθμίσεις} \quad \vec{v} = v \hat{x} \quad \Lambda(\vec{v} = v \hat{x})$$

$$t' \equiv x^0 = \gamma(x^0 - v x^1)$$

$$\frac{\partial x^0'}{\partial x^0} = \gamma$$

$$x' \equiv x^1 = \gamma(x^1 - v x^0)$$

$$\frac{\partial x^0'}{\partial x^1} = -\gamma v$$

$$y' \equiv x^2 = x^2$$

$$z' \equiv x^3 = x^3$$

$$\begin{pmatrix} dx^0 \\ dx^1 \\ dx^2 \\ dx^3 \end{pmatrix} = \begin{bmatrix} \gamma & -\gamma u & 0 & 0 \\ -\gamma u & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} dx^0 \\ dx^1 \\ dx^2 \\ dx^3 \end{pmatrix}$$

$$dx^{\mu'} = \Lambda^{\mu'}_{\mu} dx^{\mu}$$

*αναστροφός

$$\begin{pmatrix} dx_0 \\ dx_1 \\ dx_2 \\ dx_3 \end{pmatrix} = \begin{bmatrix} \frac{\partial x^0}{\partial x_0'} & \frac{\partial x^0}{\partial x_1'} & \frac{\partial x^0}{\partial x_2'} & \frac{\partial x^0}{\partial x_3'} \\ \frac{\partial x^1}{\partial x_0'} & \frac{\partial x^1}{\partial x_1'} & \frac{\partial x^1}{\partial x_2'} & \frac{\partial x^1}{\partial x_3'} \\ \frac{\partial x^2}{\partial x_0'} & \frac{\partial x^2}{\partial x_1'} & \frac{\partial x^2}{\partial x_2'} & \frac{\partial x^2}{\partial x_3'} \\ \frac{\partial x^3}{\partial x_0'} & \frac{\partial x^3}{\partial x_1'} & \frac{\partial x^3}{\partial x_2'} & \frac{\partial x^3}{\partial x_3'} \end{bmatrix} \begin{pmatrix} dx_0 \\ dx_1 \\ dx_2 \\ dx_3 \end{pmatrix}$$

T

$$dx_{\mu'} = \Lambda_{\mu'}^{\mu} dx_{\mu}$$

$$x^0 = \gamma(x^0' + u x^1')$$

$$x^1 = \gamma(x^1' + u x^0')$$

$$x^2 = x^2'$$

$$x^3 = x^3'$$

$$\frac{\partial x^0}{\partial x_0'} = \gamma$$

$$\frac{\partial x^0}{\partial x_1'} = \gamma u$$

$$\begin{pmatrix} dx_0 \\ dx_1 \\ dx_2 \\ dx_3 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} dx'_0 \\ dx'_1 \\ dx'_2 \\ dx'_3 \end{pmatrix}$$

$$dx_{\mu'} = \Lambda_{\mu'}^{\mu} dx_{\mu}$$

$A^\mu = (A^0, \vec{A}) = (A^0, A^1, A^2, A^3)$ αυτοφοιωτός ταυγάς
 \perp^{ns} ταξεως av
μετασχηματίζεται σαν dx^μ

$A_\mu = (-A^0, \vec{A})$ ευναόριωτός ταυγάς \perp^{ns} ταξεως
av μετασχηματίζεται σαν

$$\partial_\mu = \frac{\partial}{\partial x^\mu}$$

\vec{A} = ευρετικό διανυγμα (μετ. καταλήψη 6ε
3-D στροφές
και μεταπολ. 6ε's)

$$A^\mu \cdot A_\mu = A_\mu \cdot A^\mu = -(A^0)^2 + (\vec{A} \cdot \vec{A})$$

$$A^{\mu'} \cdot A_{\mu'} = (\Lambda^{\mu'}_\mu A^\mu) (\Lambda_{\mu'}^{\kappa} A_\kappa) = (\Lambda^{\mu'}_\mu \Lambda_{\mu'}^{\kappa}) A^\mu A_\kappa$$

$$A^{\mu'} A_{\mu'} = \dots = \delta_\mu^\kappa A^\mu A_\kappa = A^\mu A_\mu$$

$$\delta_\mu^\kappa = \begin{cases} 1 & \mu = \kappa \\ 0 & \mu \neq \kappa \end{cases}$$

$$\text{δινή } \Lambda_{\mu'}^{\kappa} = (\Lambda^{-1})^{\kappa}_{\mu'}$$

ΕΓΤΩ $A^{\mu} = (A^0, A^1, 0, 0)$ να βρεθούν.

a) $A_{\mu} = \begin{bmatrix} -A^0 \\ A^1 \end{bmatrix}$

b) $A^{\mu'} = \begin{bmatrix} \gamma(A^0 - \nu A^1) \\ \gamma(A^1 - \nu A^0) \end{bmatrix} = \begin{bmatrix} \gamma & -\nu \\ -\nu & \gamma \end{bmatrix} \begin{bmatrix} A^0 \\ A^1 \end{bmatrix}$

c) $A_{\mu'} = \begin{bmatrix} \gamma & \nu \\ \nu & \gamma \end{bmatrix} \begin{bmatrix} A_0 \\ A_1 \end{bmatrix}$

$(A_0 = -A^0)$
 $(A_1 = A^1)$

dia $\Lambda = \Lambda(\vec{U} = \nu \hat{x})$ (τυπολογικός μεταβ.)

$A^{\mu} = \begin{pmatrix} A^0 \\ A^1 \end{pmatrix}$

$n_{\nu\mu} A^{\mu} = A_{\nu}$

$n_{\mu\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = n^{\mu\nu}$

$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} A^0 \\ A^1 \end{bmatrix} = \begin{bmatrix} -A^0 \\ A^1 \end{bmatrix}$

$$\begin{aligned} n_{0,0}^{0,0} A^0 + n_{0,1}^{0,1} A^1 + n_{0,2}^{0,2} A^2 + n_{0,3}^{0,3} A^3 &= A_0 \\ \cancel{n_{1,0}^{0,0}} A^0 + \cancel{n_{1,1}^{0,1}} A^1 + \cancel{n_{1,2}^{0,2}} A^2 + \cancel{n_{1,3}^{0,3}} A^3 &= A_1 \\ \dots &= A_2 \\ &= A_4 \end{aligned}$$

$A^{\mu'} = \Lambda^{\mu'}_{\mu} A^{\mu}$

$\Lambda^{\mu'}_{\mu} = \begin{bmatrix} \gamma & -\nu \\ -\nu & \gamma \end{bmatrix}$

$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} n^{\mu\nu}$

$\begin{bmatrix} A^0' \\ A^1' \end{bmatrix} = \begin{bmatrix} \gamma & -\nu \\ -\nu & \gamma \end{bmatrix} \begin{bmatrix} A^0 \\ A^1 \end{bmatrix}$

$= \begin{bmatrix} \gamma(A^0 - \nu A^1) \\ \gamma(A^1 - \nu A^0) \end{bmatrix}$

$A_{\mu'} = n_{\mu' \kappa'} A^{\kappa'}$

$A_0' = n_{0,0}' A^0' + n_{0,1}' A^1' = -A^0' = -\gamma(A^0 - \nu A^1)$

$A_1' = n_{1,0}' A^0' + n_{1,1}' A^1' = A^1' = \gamma(A^1 - \nu A^0)$

$\begin{bmatrix} A_0' \\ A_1' \end{bmatrix} = \begin{bmatrix} -\gamma(-A_0 - \nu A_1) \\ \gamma(A_1 + \nu A_0) \end{bmatrix} = \begin{bmatrix} \gamma(A_0 + \nu A_1) \\ \gamma(A_1 + \nu A_0) \end{bmatrix} = \begin{bmatrix} \gamma & \nu \\ \nu & \gamma \end{bmatrix} \begin{bmatrix} A_0 \\ A_1 \end{bmatrix}$

Παραδειγμα

Δειξτε $\left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} - \frac{\partial^2}{\partial t^2} \right] \cdot \Phi(\vec{x}, t) = 0$

$$\square = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} - \frac{\partial^2}{\partial t^2}$$

εστω $\Lambda = \Lambda(\vec{U} = U \hat{x})$ $\square' = ?$

$$t' = \gamma(t - ux) = t'(t, x, y, z)$$

$$x' = \gamma(x - ut) = x'(t, x, y, z)$$

$$y' = y = y'(t, x, y, z)$$

$$z' = z = z'(t, x, y, z)$$

$$x^0 = t = \gamma(t' + ux') = t(t', x', y', z')$$

$$x' = x = \gamma(x' + ut') = x(t', x', y', z')$$

$$y^0 = y = y' = y(t', x', y', z')$$

$$z^0 = z = z' = z(t', x', y', z')$$

$$\frac{\partial t}{\partial t'} = \frac{\partial}{\partial t} [\gamma(t' + ux')] = \gamma$$

$$\frac{\partial t}{\partial x'} = \frac{\partial}{\partial x} [\gamma(t' + ux')] = \gamma u$$

$$\frac{\partial t}{\partial y'} = \frac{\partial t}{\partial z'} = 0$$

$$\frac{\partial x}{\partial t'} = \frac{\partial}{\partial t} [\gamma(x' + ut')] = \gamma u \quad \frac{\partial x}{\partial x'} = \gamma$$

$$\frac{\partial}{\partial t'} = \frac{\partial}{\partial t} \frac{\partial t}{\partial t'} + \frac{\partial}{\partial x} \frac{\partial x}{\partial t'} + \frac{\partial}{\partial y} \frac{\partial y}{\partial t'} + \frac{\partial}{\partial z} \frac{\partial z}{\partial t'}$$

$$\frac{\partial}{\partial x'} = \frac{\partial}{\partial t} \frac{\partial t}{\partial x'} + \frac{\partial}{\partial x} \frac{\partial x}{\partial x'} + \frac{\partial}{\partial y} \frac{\partial y}{\partial x'} + \frac{\partial}{\partial z} \frac{\partial z}{\partial x'}$$

$$\frac{\partial}{\partial y'} = \frac{\partial}{\partial t} \frac{\partial t}{\partial y'} + \frac{\partial}{\partial x} \frac{\partial x}{\partial y'} + \frac{\partial}{\partial y} \frac{\partial y}{\partial y'} + \frac{\partial}{\partial z} \frac{\partial z}{\partial y'}$$

$$\frac{\partial}{\partial z'} = \frac{\partial}{\partial t} \frac{\partial t}{\partial z'} + \frac{\partial}{\partial x} \frac{\partial x}{\partial z'} + \frac{\partial}{\partial y} \frac{\partial y}{\partial z'} + \frac{\partial}{\partial z} \frac{\partial z}{\partial z'}$$

$$\begin{bmatrix} \frac{\partial}{\partial t'} \\ \frac{\partial}{\partial x'} \\ \frac{\partial}{\partial y'} \\ \frac{\partial}{\partial z'} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial t}{\partial t'} & \frac{\partial x}{\partial t'} & \frac{\partial y}{\partial t'} & \frac{\partial z}{\partial t'} \\ \frac{\partial t}{\partial x'} & \frac{\partial x}{\partial x'} & \frac{\partial y}{\partial x'} & \frac{\partial z}{\partial x'} \\ \frac{\partial t}{\partial y'} & \frac{\partial x}{\partial y'} & \frac{\partial y}{\partial y'} & \frac{\partial z}{\partial y'} \\ \frac{\partial t}{\partial z'} & \frac{\partial x}{\partial z'} & \frac{\partial y}{\partial z'} & \frac{\partial z}{\partial z'} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\partial}{\partial t} \\ \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\partial}{\partial t'} \\ \frac{\partial}{\partial x'} \\ \frac{\partial}{\partial y'} \\ \frac{\partial}{\partial z'} \end{bmatrix} = \begin{bmatrix} \gamma & \gamma v & 0 & 0 \\ \gamma v & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{\partial}{\partial t} \\ \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix}$$

$$\begin{array}{l|l} \frac{\partial}{\partial t'} = \frac{\partial}{\partial t} & \frac{\partial}{\partial z'} = \frac{\partial}{\partial z} \\ \frac{\partial^2}{\partial t'^2} = \frac{\partial^2}{\partial t^2} & \frac{\partial^2}{\partial z'^2} = \frac{\partial^2}{\partial z^2} \end{array}$$

$$\begin{array}{l|l} \frac{\partial}{\partial t'} = \partial_t = \gamma \partial_t + \gamma v \partial_x & \\ \frac{\partial}{\partial x'} = \partial_{x'} = \gamma \partial_x + \gamma v \partial_t & \end{array}$$

$$\partial_{t'}(\partial_{t'}) = (\gamma \partial_t + \gamma v \partial_x)(\gamma \partial_t + \gamma v \partial_x) =$$

$$\frac{\partial^2}{\partial t'^2} = \gamma^2 \partial_t^2 + 2\gamma v \gamma \partial_x \partial_t + \gamma^2 v^2 \partial_x^2$$

$$\frac{\partial^2}{\partial x'^2} = (\gamma \partial_x + \gamma v \partial_t)(\gamma \partial_x + \gamma v \partial_t)$$

$$\partial_{x'}^2 = (\gamma^2 \partial_x^2 + 2\gamma v \gamma \partial_x \partial_t + \gamma^2 v^2 \partial_t^2)$$

$$\partial_{x'}^2 - \partial_{t'}^2 =$$

$$= \cancel{\gamma^2 \partial_x^2 + 2\gamma v \gamma \partial_x \partial_t + \gamma^2 v^2 \partial_t^2} - \cancel{\gamma^2 \partial_t^2} - \cancel{2\gamma v \gamma \partial_x \partial_t} - \cancel{\gamma^2 v^2 \partial_x^2}$$

$$= \gamma^2 \partial_x^2 - \gamma^2 v^2 \partial_x^2 - (\gamma^2 \partial_t^2 - \gamma^2 v^2 \partial_t^2)$$

$$= \gamma^2(1-v^2) \partial_x^2 - \gamma^2(1-v^2) \partial_t^2 = \partial_x^2 - \partial_t^2$$

$$\delta^2 = \frac{1}{1-v^2}$$

$$\square' = \square \sqrt{\frac{1}{\epsilon_0 \mu_0}}$$

$$\square' \phi' = 0$$

$$\square \phi = 0$$

$$\partial_\mu = \left(\frac{\partial}{\partial t}, \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

$$\partial^\mu = \left(\frac{\partial}{\partial t}, \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

$$\partial_\mu \partial^\mu \phi = \left(-\frac{\partial^2}{\partial t^2} + \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \phi = 0$$

$$\boxed{\partial_\mu \partial^\mu = \partial_\mu \partial^\mu}$$

Ταυγότες Ι^η Ταξεως στο 4D

$$x^\mu = (t, \vec{r})$$

$$dx^\mu = \boxed{\vec{r} \cdot \frac{d\vec{r}}{dt}, \frac{d^2\vec{r}}{dt^2}}$$

$$v^\mu = ()$$

$$a^\mu = ()$$

διανυσματική δεσμευτική → αναγνωρίζεται νέο κατώπιν
από ομογενείς μετ. Lorentz, Διλατηση
αυτούς που αφήνουν το $(0, 0, 0, 0)$ στην
διεύθυνση του

$$\text{Δοκιμαζω το } v^\mu = \frac{dx^\mu}{dt} = \frac{d}{dt}(t, x, y, z) = \left(\frac{dt}{dt}, \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right) = (1, u_x, u_y, u_z)$$

$$\text{η.χ. } \wedge (v = u\hat{x})$$

$$v^\mu = \left(\frac{dt'}{dt}, \frac{dx'}{dt}, \frac{dy'}{dt}, \frac{dz'}{dt} \right)$$

$$dt' = \gamma(dt - v dx)$$

$$dx' = \gamma(dx - v dt)$$

$$dy' = dy$$

$$dz' = dz$$

$$\frac{dx'}{dt'} = \frac{\gamma(dx - v dt)}{\gamma(dt - v dx)} = \frac{\frac{dx}{dt} - v}{1 - v \cdot \frac{dx}{dt}}$$

$$u'_x = \frac{u_x - v}{1 - v \cdot u_x}$$

$$u'_y = \frac{dy'}{dt'} = \frac{dy}{\gamma(dt - v dx)} = \frac{u_y / \gamma}{1 - v \cdot u_x}$$

$$u'_z = \frac{dz'}{dt'} = \frac{dz}{\gamma(dt - v dx)} = \frac{u_z / \gamma}{1 - v \cdot u_x}$$

$$u^\mu = (1, \frac{u_x - v}{1 - v \cdot u_x}, \frac{u_y / \gamma}{1 - v \cdot u_x}, \frac{u_z / \gamma}{1 - v \cdot u_x})$$

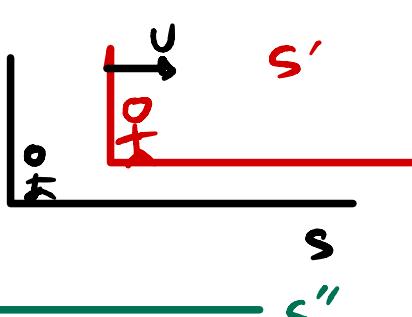
δεν μετ. σαν
ταυγότες Ι^η
ταξεως

$$u^0' = \gamma(u^0 - vu^1)$$

$$u^1' = \gamma(u^1 - vu^0)$$

$$\begin{aligned} dt'^2 - (dx')^2 - (dy')^2 - (dz')^2 &= (dt)^2 - (dx)^2 - (dy)^2 - (dz)^2 \\ dt' = d\tau &= (dt)^2 \left(1 - \frac{dx^2}{dt^2} - \frac{dy^2}{dt^2} - \frac{dz^2}{dt^2}\right) \\ \frac{dx'}{dt'} = 0 &= (dt)^2 \left(1 - \vec{v} \cdot \vec{v}\right) = dt^2 / \gamma^2 \\ \frac{dy'}{dt'} = 0 \\ \frac{dz'}{dt'} = 0 \end{aligned}$$

$$\gamma d\tau = dt$$

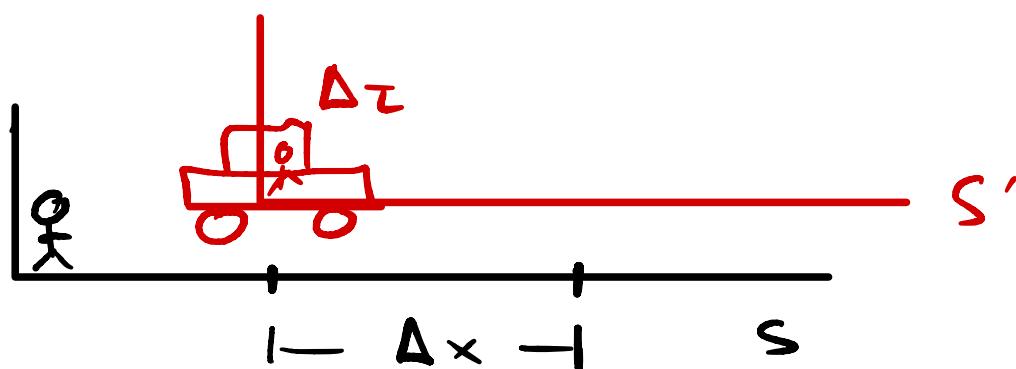


$$U^{\mu} = \frac{dx^{\mu}}{d\tau} = \gamma \frac{dx^{\mu}}{dt} = (\gamma, \gamma \vec{v})$$

$$\frac{\Delta x^{\mu}}{\Delta \tau}$$

$$U^{\mu'} = \Lambda^{\mu'}_{\mu} U^{\mu}$$

$$U_{\mu} = (-\gamma, \gamma \vec{v})$$

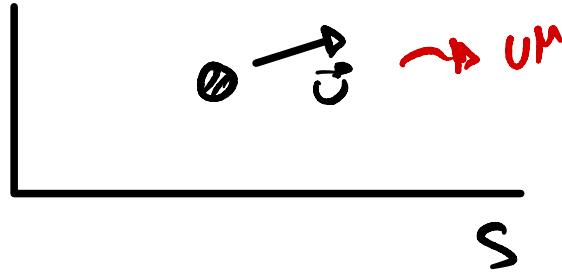


$$U^{\mu} U_{\mu} = -\gamma^2 + \gamma^2 \vec{v} \cdot \vec{v} = -\gamma^2 + \gamma^2 v^2 = -\gamma^2 (1 - v^2) = \frac{-1}{1-v^2} (1-v^2) = -1$$

$|\vec{v}| = v$

$$U^{\mu} \cdot U_{\mu} = U_{\mu} \cdot U^{\mu'} = -1$$

$$U^{\mu} = (\gamma, \gamma \vec{v})$$



$$U^{\mu'} = (\gamma', \gamma' \vec{v}') = (1, \vec{0})$$

s' συστήμα ηρεμίας

$$U^{\mu} \cdot U_{\mu} = U^{\mu'} \cdot U_{\mu'} = (-1, \vec{0}) \cdot (1, \vec{0}) = -1$$

$$a^{\mu} = \frac{dU^{\mu}}{d\tau} = \gamma \frac{dU^{\mu}}{dt} = \gamma \frac{d}{dt} (\gamma, \gamma \vec{v})$$

$$\dot{\gamma} = \frac{d}{dt}(\gamma) = \frac{d}{dt} \left([1 - \vec{v} \cdot \vec{v}]^{-1/2} \right) = -\frac{1}{2} (1 - \vec{v} \cdot \vec{v})^{-3/2} (-2 \vec{v} \cdot \frac{d\vec{v}}{dt})$$

$$\dot{\gamma} = \gamma^3 (\vec{v} \cdot \vec{a})$$

$$a^{\mu} = \gamma \frac{d}{dt} (\gamma, \gamma \vec{v}) = \gamma (\gamma^3 (\vec{v} \cdot \vec{a}), \frac{d}{dt} (\gamma \vec{v})) =$$

$$\frac{d}{dt} (\gamma \vec{v}) = \dot{\gamma} \vec{v} + \gamma \cdot \frac{d\vec{v}}{dt} = \gamma^3 (\vec{v} \cdot \vec{a}) \vec{v} + \gamma \cdot \vec{a}$$

$$a^{\mu} = (\gamma^3 (\vec{v} \cdot \vec{a}), \gamma^3 (\vec{v} \cdot \vec{a}) \cdot \vec{v} + \gamma^2 \vec{a})$$

$$a^{\mu} a_{\mu} = (\vec{a}_0)^2$$

$\uparrow, \delta, \text{ο επιταχυνση}$

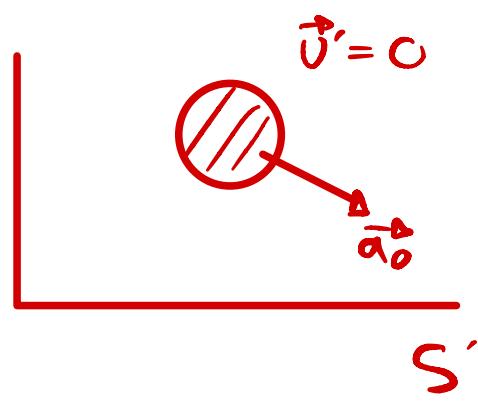
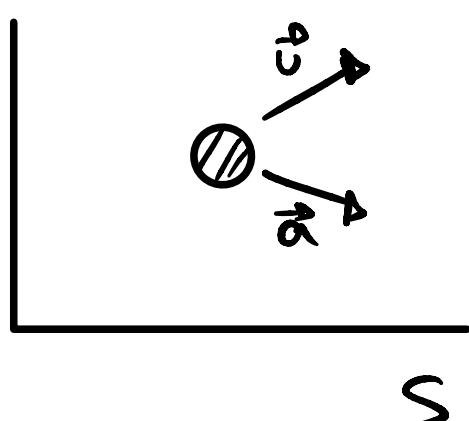
$$\begin{aligned}
 a^\mu a_\mu &= \left(\gamma^4(\vec{v} \cdot \vec{\alpha}), \gamma^4(\vec{v} \cdot \vec{\alpha}) \cdot \vec{v} + \gamma^2 \vec{\alpha} \right) \left(-\gamma^4(\vec{v} \cdot \vec{\alpha}), \gamma^4(\vec{v} \cdot \vec{\alpha}) \cdot \vec{v} + \gamma^2 \vec{\alpha} \right) \\
 &= -\gamma^8 (\vec{v} \cdot \vec{\alpha})^2 + \gamma^8 (\vec{v} \cdot \vec{\alpha})^2 \cdot v^2 + 2\gamma^6 (\vec{v} \cdot \vec{\alpha})^2 + \gamma^4 (\vec{\alpha})^2 \\
 &= -\gamma^8 (\vec{v} \cdot \vec{\alpha})^2 \left(1 - \frac{v^2}{\gamma^2} \right) + 2\gamma^6 (\vec{v} \cdot \vec{\alpha})^2 + \gamma^4 (\vec{\alpha})^2 \\
 &= -\gamma^6 (\vec{v} \cdot \vec{\alpha})^2 + 2\gamma^6 (\vec{v} \cdot \vec{\alpha})^2 + \gamma^4 (\vec{\alpha})^2
 \end{aligned}$$

$$a^\mu a_\mu = \gamma^6 (\vec{v} \cdot \vec{\alpha})^2 + \gamma^4 (\vec{\alpha})^2 = (\vec{\alpha}_0)^2$$

κ. διεπιταχυνγή

- $\vec{\alpha} \parallel \vec{v}$ τότε $a^\mu a_\mu = \gamma^6 v^2 \alpha^2 + \gamma^4 \alpha^2$
 $= \gamma^4 \alpha^2 (1 + \gamma^2 v^2)$
 $= \gamma^4 \alpha^2 \left(\frac{1-v^2}{1+v^2} + \frac{v^2}{1+v^2} \right)$
 $= \gamma^6 \alpha^2 = \gamma^6 (\vec{\alpha})^2$
 $|\vec{\alpha}_0| = \gamma^3 |\vec{\alpha}|$

- $\vec{\alpha} \perp \vec{v}$ τότε $a_\nu \cdot a^\mu = \gamma^4 (\vec{\alpha})^2 = \gamma^4 \alpha^2$
 $|\vec{\alpha}_0| = \gamma^2 |\vec{\alpha}|$



Επίμονο
ευεύηχα
αναφοράς ονο
το σώμα είναι
GE πρέμα

$$\begin{matrix} \gamma' = 1 \\ v' = 0 \end{matrix}$$

$$\begin{aligned}
 a^\mu &= \left(\gamma^4(\vec{v} \cdot \vec{\alpha}), \gamma^4(\vec{v} \cdot \vec{\alpha}) \cdot \vec{v} + \gamma^2 \vec{\alpha} \right) \\
 v^\mu &= (\gamma, \gamma \vec{v})
 \end{aligned}$$

$$a^\mu = (0, \vec{\alpha}_0)$$

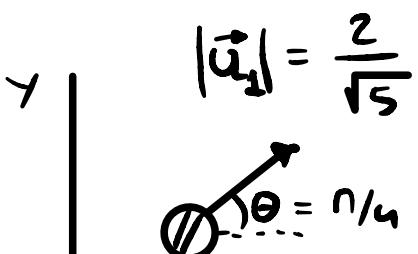
$$v^\mu = (1, \vec{0})$$

$$a^\mu \cdot v_\mu = a^\mu \cdot v_\mu = 0$$

$$\frac{d}{dt} (v^\mu \cdot v_\mu) = \frac{d}{dt} (-1)$$

$$v^\mu \cdot a_\mu + a^\mu \cdot v_\mu = 0$$

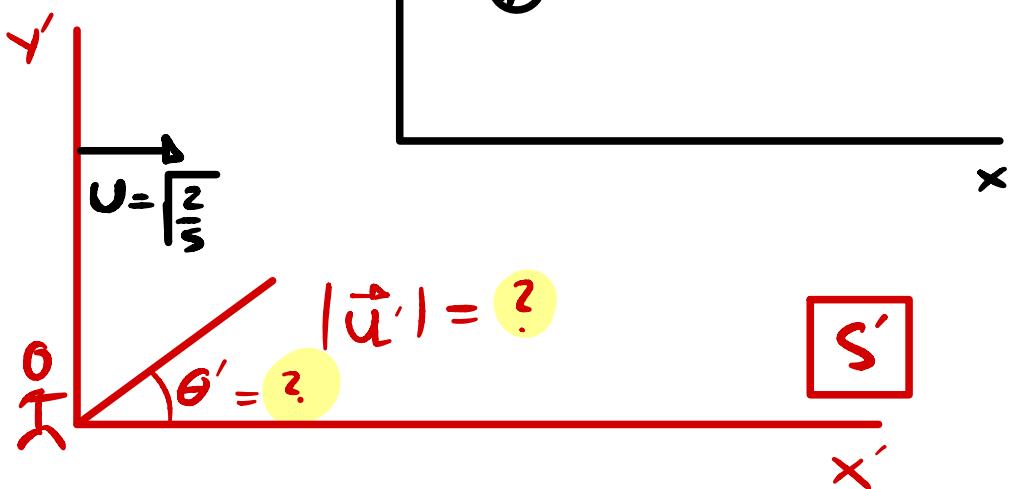
$$2v^\mu \cdot a_\mu = 2a_\mu \cdot v^\mu = 0$$

 \boxed{S}

$\lambda(\vec{u} = \sqrt{\frac{2}{5}} \hat{x})$

$$\begin{aligned}\hat{x}' &= \hat{x} \\ \hat{y}' &= \hat{y} \\ \hat{z}' &= \hat{z}\end{aligned}$$

α τρόπος

 $\boxed{S'}$

$\vec{u}_1 = \left(\frac{\sqrt{2}}{\sqrt{5}}, \frac{\sqrt{2}}{\sqrt{5}}, 0 \right)$

$\delta_{11} = \frac{1}{\sqrt{1 - 4/5}} =$

$u_1^r = \left(\sqrt{5}, \sqrt{2}, \sqrt{2}, 0 \right)$

$$u_1^r = \begin{pmatrix} \frac{\sqrt{5}}{3} & -\frac{\sqrt{2}}{3} & 0 & 0 \\ -\frac{\sqrt{2}}{3} & \frac{\sqrt{5}}{3} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{bmatrix} \sqrt{5} \\ \sqrt{2} \\ \sqrt{2} \\ 0 \end{bmatrix}$$

$\delta = \frac{1}{\sqrt{1 - 2/5}} = \sqrt{\frac{5}{3}}$

$\delta^r = \sqrt{\frac{5}{3}} \cdot \sqrt{\frac{2}{5}} = \sqrt{\frac{2}{3}}$

$$= \begin{bmatrix} \frac{5}{\sqrt{3}} & -\frac{2}{\sqrt{3}} \\ -\frac{\sqrt{10}}{\sqrt{3}} & +\frac{\sqrt{10}}{\sqrt{3}} \\ \sqrt{2} \\ 0 \end{bmatrix} = \begin{bmatrix} \sqrt{3} \\ 0 \\ \sqrt{2} \\ 0 \end{bmatrix} = \delta'_1 \begin{bmatrix} 1 \\ u_{1x}' \\ u_{1y}' \\ u_{1z}' \end{bmatrix}$$

$$\begin{aligned}u_1^r \cdot u_{1r} &= -1 \\ -3 + 2 &= -1 \\ \checkmark \text{OK} &\end{aligned}$$

$\delta'_1 = \sqrt{3}$

$\delta'_1 \cdot u_{1x}' = 0$

$u_{1x}' = 0$

$\Theta' = \frac{\pi}{2}$

$\delta'_1 \cdot u_{1y}' = \sqrt{2}$

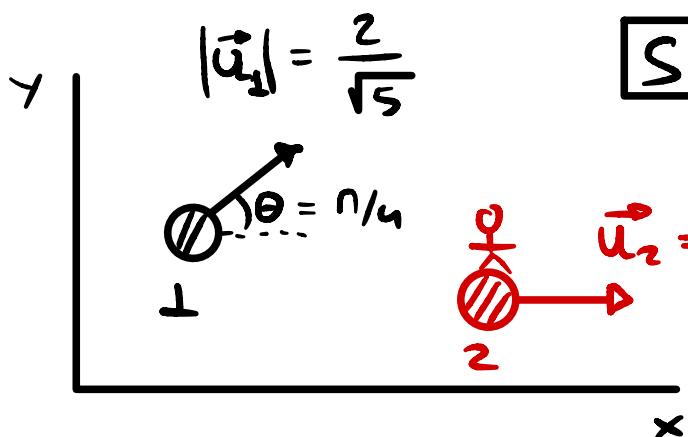
$u_{1y}' = \sqrt{2}/\sqrt{3}$

$|\vec{u}_1'| = \sqrt{2}/\sqrt{3}$

$\delta'_1 \cdot u_{1z}' = 0$

$u_{1z}' = 0$

β τρόπος

 \boxed{S}

$\vec{u}_{12} = \vec{u}_1'$

$u_1^r \quad u_2^r \quad \boxed{S}$

$\vec{u}_2 = (\sqrt{\frac{2}{5}}, 0, 0)$

 $\boxed{S'}$

$u_1^r \quad u_2^r \quad \boxed{S}$

 $\boxed{S'}$

$u_1^r \cdot u_{2r} = u_1^r \cdot u_{2r}$

$\delta_2 = \frac{1}{\sqrt{1 - 2/5}} = \sqrt{5/3}$

$$u_1^{\mu} = \left(\sqrt{5}, \sqrt{2}, \sqrt{2}, 0 \right) \quad | \quad u_1^{\nu} = (\gamma_1', \gamma_1' \vec{v}_1')$$

$$u_2^{\mu} = \left(\frac{\sqrt{5}}{\sqrt{3}}, \sqrt{\frac{2}{3}}, 0, 0 \right) \quad | \quad u_2^{\nu} = (1, 0)$$

$$u_1^{\mu} \cdot u_{2\mu} = u_1^{\nu} \cdot u_{2\nu}$$

$$\left(-\sqrt{5} \sqrt{\frac{5}{3}} + \sqrt{2} \sqrt{\frac{2}{3}} + 0 \cdot \sqrt{2} + 0 \cdot 0 \right) = -\gamma_1' + 0$$

$$\gamma_1' = \sqrt{3} = \frac{1}{\sqrt{1 - (\vec{v}_1')^2}} =$$

$$|\vec{u}_1'|^2 = \frac{2}{3}$$

$$u_2^{\mu} = \begin{bmatrix} \sqrt{\gamma_3} \\ \sqrt{2/3} \\ 0 \\ 0 \end{bmatrix} \quad u_2^{\nu} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{pmatrix} \sqrt{\frac{5}{3}} & -\sqrt{\frac{2}{3}} & 0 & 0 \\ -\sqrt{\frac{2}{3}} & \sqrt{\frac{5}{3}} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{bmatrix} \sqrt{\gamma_3} \\ \sqrt{2/3} \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad \checkmark$$

Υνερβοδική κίνηση

Κίνησης γωνίας με σταθερή ιδιόενταχυγή $\vec{\alpha}_0 = \alpha_0 \hat{z}$

Κλασική μέθοδος

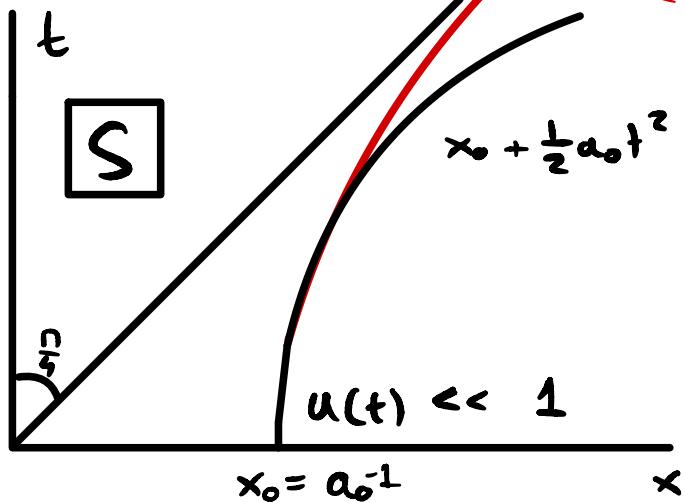
$$x(t) = x_0 + \frac{1}{2} \alpha_0 t^2$$

$$v_x(t) = \alpha_0 t + v_0^0$$

$$v_y(t) = v_z(t) = 0$$

↓ Επιμένουσες αναφοράς

$$\alpha^r = (0, \alpha_0, 0, 0)$$



$$\alpha^r = (\gamma^4(\vec{v} \cdot \vec{\alpha}), \gamma^4(\vec{v} \cdot \vec{\alpha}) \cdot \vec{v} + \gamma^2 \vec{\alpha})$$

$$(u = v)$$

$$\alpha^r \cdot \alpha_p = \alpha_0^2 = (\gamma^3 \alpha)^2$$

$$\vec{\alpha} = (\alpha, 0, 0) \quad \boxed{S}$$

$$\leftarrow \alpha_0 = \gamma^3 \alpha = \frac{d}{dt}(\gamma \vec{v})$$

αποδείξη:

$$\frac{d}{dt}(\gamma \vec{v}) = \dot{\gamma} \vec{v} + \gamma \cdot \frac{d\vec{v}}{dt} = \gamma^3 (\vec{v} \cdot \vec{\alpha}) \vec{v} + \gamma \cdot \vec{\alpha}$$

$$\begin{aligned} \vec{v} \cdot \vec{\alpha} &= \gamma^3 v^2 \alpha + \gamma \alpha = \gamma(1 + \gamma^2 v^2) \alpha = \gamma \left(\frac{1 - v^2}{1 + v^2} + \frac{v^2}{1 + v^2} \right) \alpha \\ &= \gamma^3 \alpha \end{aligned}$$

$$\frac{d}{dt}(\gamma v) = \alpha_0$$

$$\gamma v = \alpha_0 t + v_0^0$$

$$(\gamma v)^2 = (\alpha_0 t)^2$$

$$v^2 = (\alpha_0 t)^2 (1 - v^2)$$

$$(1 + (\alpha_0 t)^2) v^2 = (\alpha_0 t)^2$$

$$v(t) = \frac{\alpha_0 t}{\sqrt{1 + (\alpha_0 t)^2}}$$

$$\lim_{\alpha_0 t \rightarrow 0} v(t) \approx \alpha_0 t$$

$$\lim_{t \rightarrow \infty} v(t) = 1$$

$$\int dx = \int \frac{a_0 t}{\sqrt{1 + (a_0 t)^2}} dt = \int \frac{\omega}{\sqrt{1 + \omega^2}} \frac{dw}{a_0} = \int (\sqrt{1 + \omega^2})' \frac{dw}{a_0}$$

$w = a_0 t$
 $dw = a_0 dt$
 $dt = \frac{dw}{a_0}$

$x(t) = \frac{1}{a_0} \sqrt{1 + (a_0 t)^2} + \cancel{C}$
 $x(0) = x_0 = \frac{1}{a_0}$
 $[U] = \text{app. 2 pos}$
 $[a_0] = \mu \text{ m s}^{-1}$

$$x^2 = \left(\frac{1}{a_0}\right)^2 + t^2$$

$$x^2 - t^2 = \left(\frac{1}{a_0}\right)^2$$

E.g. unexpanding

$$d\tau = dt$$

$$d\tau = \sqrt{(1 - u^2)} dt$$

$$d\tau^2 = \left(1 - \frac{(a_0 t)^2}{1 + (a_0 t)^2}\right) dt^2$$

$$\int_0^T d\tau' = \int_0^t \frac{1}{\sqrt{1 + (a_0 t')^2}} dt' = \int_0^{\text{arsinh}(a_0 t)} \frac{\cosh w}{\sqrt{1 + \sinh^2 w}} \frac{dw}{a_0}$$

$$\cosh^2 x - \sinh^2 x = 1$$

$$\cosh x = \frac{1}{2}(e^x + e^{-x})$$

$$\sinh w = a_0 t'$$

$$\sinh x = \frac{1}{2}(e^x - e^{-x})$$

$$\cosh w dw = a_0 dt'$$

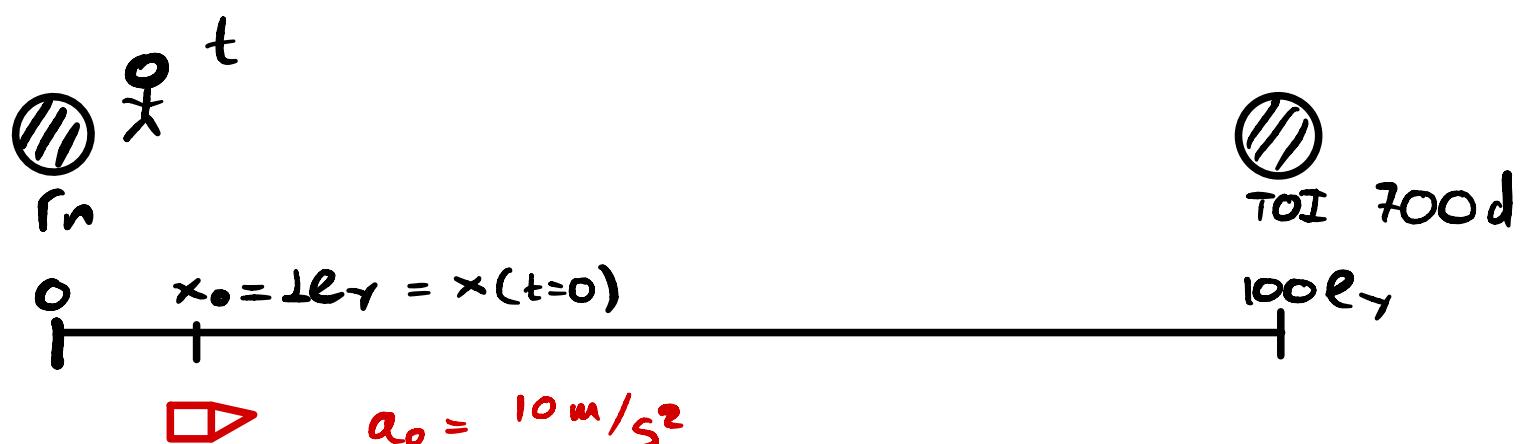
$$\tau(t) = \frac{1}{a_0} \text{arsinh}(a_0 t)$$

$$dt = \frac{\cosh w}{a_0} dw$$

$$\text{arsinh } x = \ln(x + \sqrt{1+x^2})$$

t'	0	t
w	0	$\text{arsinh}(a_0 t)$

$$\tau(t) = \frac{1}{a_0} \ln(a_0 t + \sqrt{1 + (a_0 t)^2})$$



$$\tau(t) = \frac{1}{a_0} \ln(a_0 t + \sqrt{1 + (a_0 t)^2})$$

$t_{100} = 0$ χρόνος νωρίτερα όταν η μεταβολή της θέσης είναι

$$x^2 - r^2 = \left(\frac{1}{a_0}\right)^2 \xrightarrow{\text{s.I.}} x^2 - (ct)^2 = \left(\frac{c^2}{a_0}\right)^2$$

$$t_{100} = \sqrt{\left(-\left(\frac{c^2}{a_0}\right)^2 + d^2\right)/c} \approx 99.9 \gamma \quad (3.15 \times 10^9 \text{ s})$$

με ευάρεστη προσέγγιση

$$x(0) = x_0 = c \frac{t_{100}}{a_0} = 0.95 \text{ ly}$$

$$\tau_{100}(t) = \frac{c}{a_0} \ln\left(\frac{a_0 t_{100}}{c} + \sqrt{1 + \left(\frac{a_0 t_{100}}{c}\right)^2}\right) \approx \dots \text{ Sy}$$

$$\varepsilon = \frac{a_0 t}{c}$$

$$\tau(\varepsilon) = \frac{c}{a_0} \ln(\varepsilon + \sqrt{1 + \varepsilon^2})$$

για $\varepsilon \ll 1$

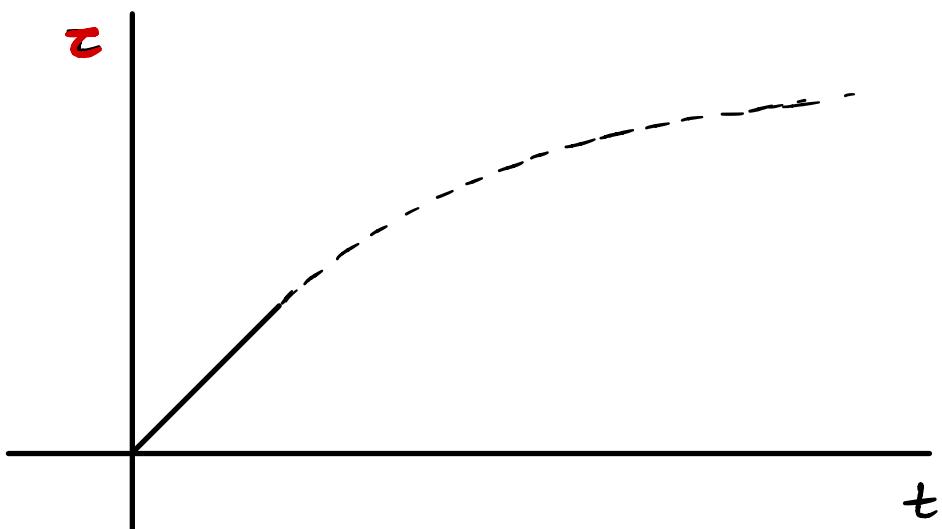
$$\tau'(\varepsilon) = \frac{c}{a_0} \frac{1}{\varepsilon + \sqrt{1 + \varepsilon^2}} \left(1 + \frac{\varepsilon}{\sqrt{1 + \varepsilon^2}} \right)$$

$$\tau(\varepsilon) \approx \tau(0) + \varepsilon \cdot \tau'(0) + \frac{1}{2!} \varepsilon^2 \tau''(0) + \dots$$

$$\approx 0 + \varepsilon \cdot \frac{c}{a_0} = t$$

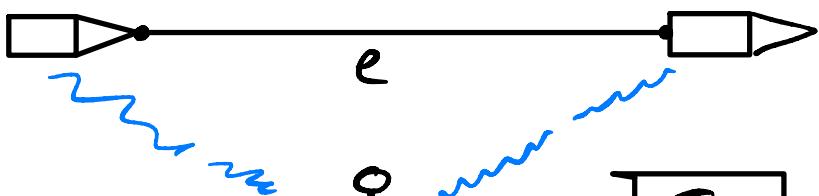
για $\varepsilon \gg 1$

$$\tau(\varepsilon) = \frac{c}{a_0} \ln(\varepsilon + \sqrt{1 + \varepsilon^2}) \approx \frac{c}{a_0} \ln(2\varepsilon)$$



μπορεί το $\varepsilon = \frac{a_0 t}{c}$ να γίνει $\varepsilon \gg 1$;

Παραδοξό του Bell



$t=0$

S

$x_1(t)$

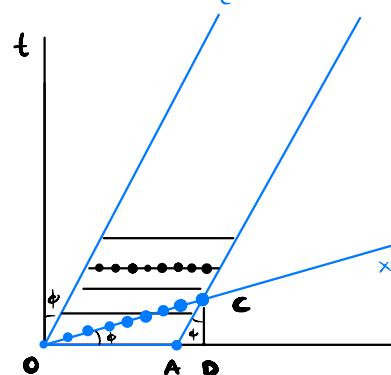
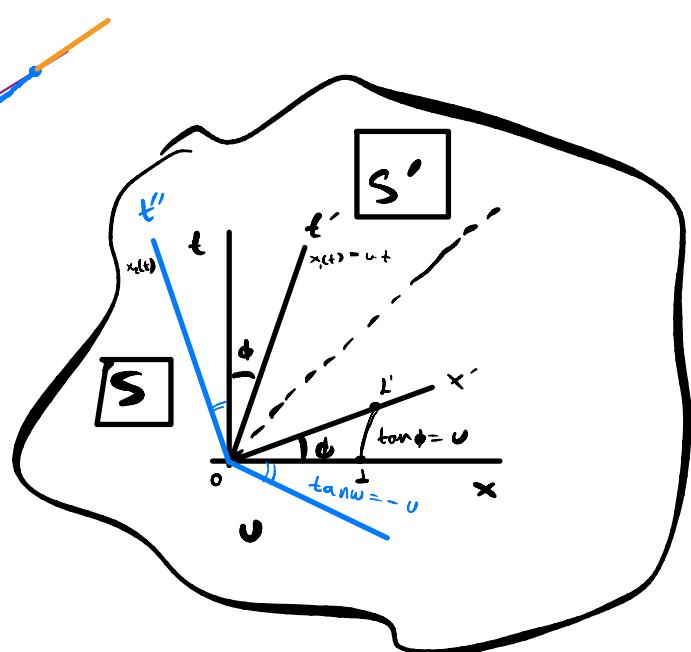
$x_2(t)$

$x_b(\tau_b)$

τ_a

$$x_0 = \frac{1}{\alpha_0}$$

$$x_0 + d$$



$$1: x_1^2 - t^2 = \left(\frac{1}{\alpha_0}\right)^2 = x_0^2$$

$$2: x_2^2 - t^2 = (x_0 + d)^2 \quad \leftarrow \text{Διάδοση διατί } x_2 = x_1 - d$$

$$v(t) = \frac{\alpha_0 t}{\sqrt{1 + (\alpha_0 t)^2}} = v_1(t) = v_2(t)$$

$$1: x_1(t) = \frac{1}{\alpha_0} \sqrt{1 + (\alpha_0 t)^2}$$

$$2: x_2(t) = \frac{1}{\alpha_0} \sqrt{1 + (\alpha_0 t)^2} + d$$

$$x_2(t) - x_1(t) = d$$

$$\frac{dx_2}{dt} = \frac{dx_1}{dt} = \frac{\alpha_0 t}{\sqrt{1 + (\alpha_0 t)^2}}$$

$$\vec{P}_{KM} = m \vec{U} \quad KM \rightarrow p^\mu = m \cdot u^\mu \quad (4\text{-Oppn})$$

$$E = \frac{m}{\sqrt{1-u^2}} \approx m \left(1 + \frac{1}{2} \cdot x + \dots \right)$$

$$f(x) = \frac{1}{\sqrt{1-x}} \quad \left| \begin{array}{l} f(x) = f(0) + x \cdot f'(0) \\ \quad \quad \quad + \dots \end{array} \right.$$

$$x = u^2$$

$$f'(x) = -\frac{1}{2} (1-x)^{-\frac{3}{2}} \cdot (-1) = \frac{1}{2} (1-x)^{-\frac{3}{2}}$$

$$f(0) = 1 \quad f'(0) = \frac{1}{2}$$

$$E = m + \frac{m u^2}{2} + \dots$$

$$= m + \frac{P_{KM}^2}{2m} + \dots$$

$$T = E - m$$

$$|\vec{P}| = 6500 \text{ GeV}$$

$$u = ?$$

Mit großer p^μ ?

$$p^\mu \cdot p_\mu \stackrel{?}{=} -m^2 = (gm, m\vec{v}) \cdot (-gm, m\vec{v})$$

$$p^\mu = (E, \vec{p})$$

$$p_\mu \cdot p^\mu = -E^2 + |\vec{p}|^2$$

$$p_\mu = (-E, \vec{p})$$

$$= -E^2 + p^2$$

$$= -\vec{p}^2 m^2 + m^2 \vec{v}^2 u^2$$

$$= -\vec{p}^2 m^2 (1 - u^2)$$

$$= -m^2 \quad (-+++)$$

$$-E^2 + p^2 = -m^2 \rightarrow$$

$$E^2 = m^2 + p^2$$

$$\vec{U} = \frac{\vec{P}}{E}$$

$$p^\mu \cdot p_\mu = m u^\mu \cdot m u_\mu = -m^2$$

$$[p^2 = m^2 \quad (+---)]$$

$$u^\mu \cdot u_\mu = -1$$

$$p^\mu = \phi \omega \tau. \quad ?$$

$$E = h \cdot v$$

$$[h] = \text{J} \cdot \text{s}$$

$$|\vec{p}| = h/\lambda$$

$$[v] = \text{s}^{-1} = \text{Hz}$$

$$2 \cdot v = c = 1$$

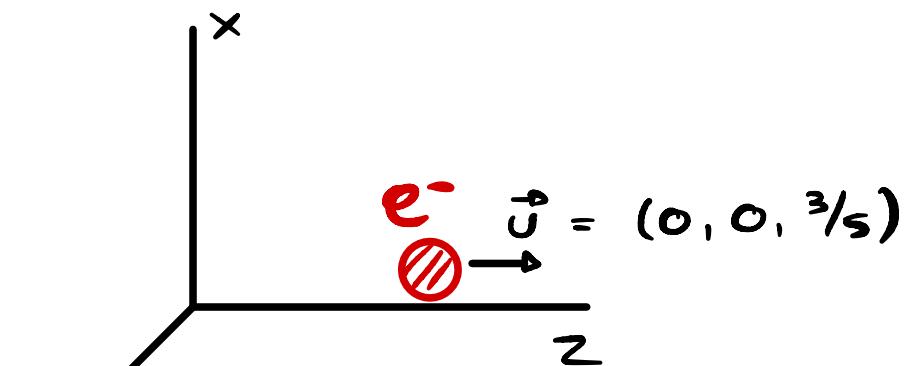
$$\hat{n} = \frac{\vec{P}}{|\vec{P}|}$$

$$\vec{P} = \frac{m \vec{U}}{\sqrt{1-u^2}}$$

$$m = m_0$$

$$P^M \quad \left| \begin{array}{l} m > 0 \\ \begin{bmatrix} m\gamma \\ m\vec{p}\cdot\hat{\vec{v}} \end{bmatrix} = \begin{bmatrix} E \\ \vec{p} \end{bmatrix} = \begin{bmatrix} \sqrt{m^2 + p^2} \\ \vec{p} \end{bmatrix} \end{array} \right| \quad \left| \begin{array}{l} m = 0 \\ \begin{bmatrix} E_\gamma \\ \vec{p}_\gamma \end{bmatrix} = \begin{bmatrix} h\nu \\ h\nu \hat{\vec{n}} \end{bmatrix} = \begin{bmatrix} \sqrt{h\nu^2 + p^2} \\ \vec{p} \end{bmatrix} = \begin{bmatrix} p \\ \vec{p} \end{bmatrix} = \begin{bmatrix} E \\ E\hat{\vec{n}} \end{bmatrix} \end{array} \right.$$

$$P^M(e^-) \quad \mu \in \quad v_z = \frac{3}{5}, \quad m_{e^-}$$



$$\left| \frac{d\vec{r}}{dt} \right| = \frac{dz}{dt} = v_z$$

$$\gamma = \frac{1}{\sqrt{1 - (\frac{3}{5})^2}} = \frac{5}{4}$$

$$\gamma_v = \frac{5}{4} \cdot \frac{3}{5} = \frac{3}{4}$$

$$m_e (= 511 \text{ keV})$$

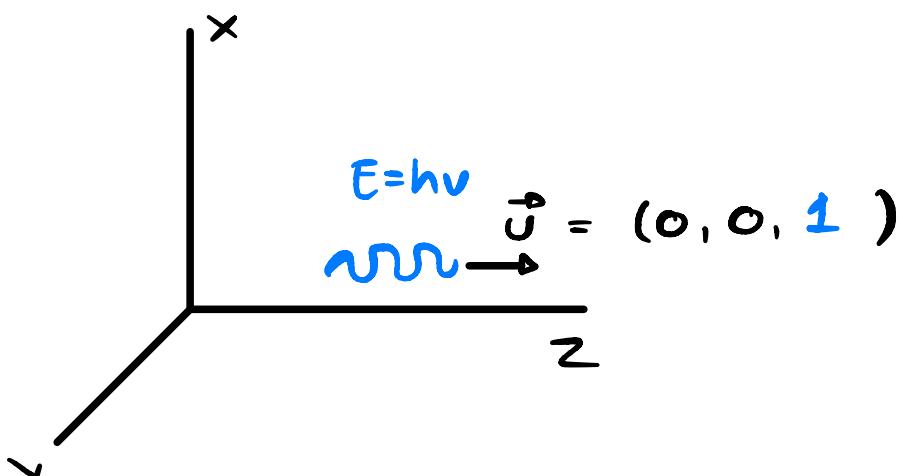
$$P^M = \left(\frac{5m}{4}, 0, 0, \frac{3m}{4} \right)$$

$$P^M \cdot P_M = -m^2 = -m^2 \left(\frac{25}{16} - \frac{9}{16} \right)$$

$$\boxed{\vec{v} = \frac{\vec{p}}{E}}$$

$$= \frac{\gamma m \vec{v}}{E}$$

$$P^M(\gamma) \quad v = 1, \quad m = 0, \quad E = h\nu, \quad \hat{\vec{n}} = (0, 0, 1)$$



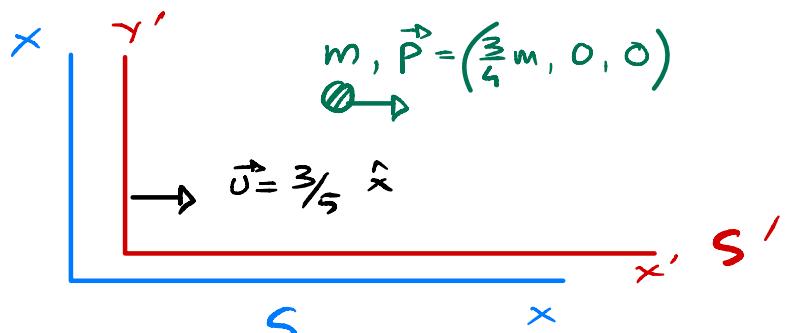
$$P^M(\gamma) = (h\nu, 0, 0, h\nu) = \begin{bmatrix} E \\ 0 \\ 0 \\ E \end{bmatrix}$$

Άσκηση 1

$$A_v \quad P^v = \left(\frac{5m}{4}, \frac{3m}{4}, 0, 0 \right)$$

$$P^{v'} = \Lambda^{v'}_v (\vec{U} = \frac{3}{5} \hat{x}) P^v \quad (TM\Lambda)$$

$$P^{v'} = ?$$



$$P^{v'} = \Lambda^{v'}_v P^v \quad | \quad P' = \Lambda \cdot P$$

$$P^v = \left(\frac{5m}{4}, \frac{3m}{4}, 0, 0 \right)$$

$$P^{v'} = (E', P'_x, P'_y, P'_z)$$

$$E' = ?$$

- a) $\frac{5}{4}m$
- b) $2m$
- c) m
- d) $\frac{3}{5}m$

$$\vec{U} = \frac{\vec{P}}{E} = \frac{0_u m \vec{U}}{E_u m} = \left(\frac{3}{5}, 0, 0 \right)$$

$$\gamma_u = \frac{1}{\sqrt{1 - (\frac{3}{5})^2}} = \frac{5}{4}$$

$$S : E^2 = P^2 + m^2$$

$$\gamma = \gamma_u = \frac{5}{4}$$

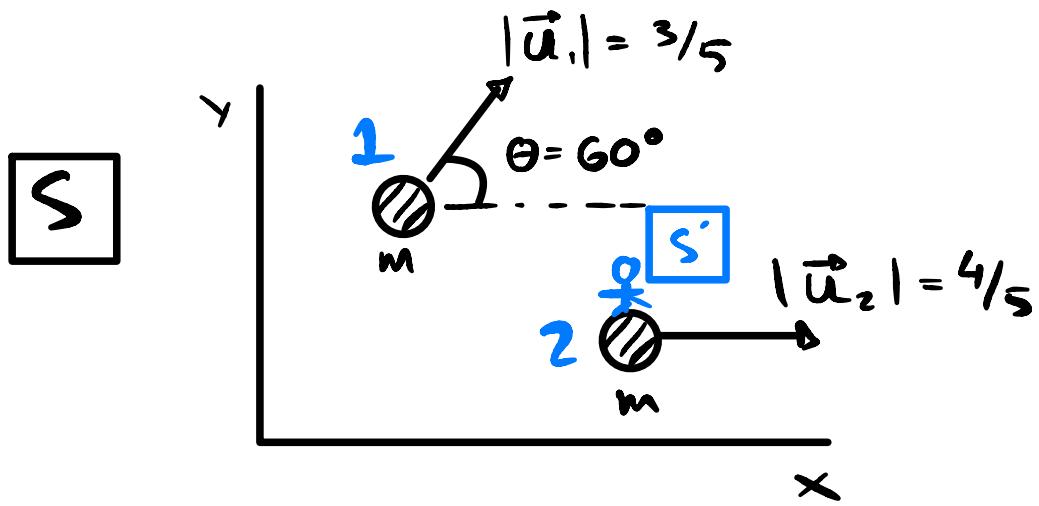
$$S' : (E')^2 = m^2$$

$$U = u = \frac{3}{5}$$

$$P^{v'} = \begin{pmatrix} \gamma & -\gamma U_x & 0 & 0 \\ -\gamma U_x & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} E \\ P_x \\ P_y \\ P_z \end{pmatrix} = \begin{pmatrix} \gamma_{\frac{5}{4}} & -\frac{3}{4} & 0 & 0 \\ -\frac{3}{4} & \frac{5}{4} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{5m}{4} \\ \frac{3m}{4} \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} m \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

ΤΕΤΡΑΟΦΥΝ
ΕΙΩΣ ΕΛΛΑΣΙΔΙΟΥ
ΓΤΟ ΕΛΛΗΝΙΚΑ
ΗΡΕΜΙΑΣ ΤΟΥ

Άσκηση 2



A_v S' = ευθύνη ηρεμίας του 2

a) E_i, \vec{P}_i, T_i στα S, S'

β) Η ταχύτητα του 1 για S' (ευθύνη ηρεμίας του 2)

$$\cos 60 = \frac{1}{2} \quad \sin 60 = \sqrt{3}/2$$

$$\vec{U}_1 = \frac{3}{5} (\cos \theta, \sin \theta, 0) = \left(\frac{3}{10}, \frac{3\sqrt{3}}{10}, 0 \right)$$

$$\vec{U}_2 = \left(\frac{4}{5}, 0, 0 \right)$$

$$\gamma_1 = \frac{5}{4}$$

$$\gamma_2 = \frac{5}{3}$$

$$P_1^\mu = (m\gamma_1, \frac{\vec{P}_1}{m\gamma_1})$$

$$P_2^\mu = (m\gamma_2, \frac{\vec{P}_2}{m\gamma_2})$$

$$P_1^\mu = m \begin{pmatrix} 5/4 \\ 3/8 \\ 3\sqrt{3}/8 \\ 0 \end{pmatrix}$$

$$P_2^\mu = m \begin{pmatrix} 5/3 \\ 4/3 \\ 0 \\ 0 \end{pmatrix}$$

$$\Lambda = \begin{pmatrix} 5/3 & -4/3 & 0 & 0 \\ -4/3 & 5/3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{d.o.f. } m = 1 \text{ GeV}$$

$$P_1^2 = -\frac{25}{16} + \frac{9}{64} + \frac{27}{64} = -\frac{100}{64} + \frac{36}{64} = -1 \quad | \quad P_2^2 = -\frac{25}{9} + \frac{16}{9} = -1 \quad [\text{GeV}^2]$$

$$P_2^{\mu'} = m \begin{pmatrix} 5/3 & -4/3 & 0 & 0 \\ -4/3 & 5/3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 5/3 \\ 4/3 \\ 0 \\ 0 \end{pmatrix} = m \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$T_i' = E_i' - m \quad | \quad l=1,2$$

$$\vec{U}_i' = \frac{\vec{P}_i'}{E_i'} \quad | \quad T_1' = \frac{19m}{12} - m = \frac{7m}{12}$$

$$T_2' = 0$$

$$P_1^{\mu'} = m \begin{pmatrix} 5/3 & -4/3 & 0 & 0 \\ -4/3 & 5/3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 5/4 \\ 3/8 \\ 3\sqrt{3}/8 \\ 0 \end{pmatrix} = m \begin{pmatrix} 19/12 \\ -25/24 \\ 3\sqrt{3}/8 \\ 0 \end{pmatrix}$$

$$\vec{U}_1' = \frac{\vec{P}_1'}{E_1'} = \frac{[-25, 9\sqrt{3}, 0]}{38}^T$$

$$|\vec{U}_1'| \approx 0.78 \quad \vec{U}_{12}' = \vec{U}_1'$$

$$E_1' = 19/12 m \quad E_1 = 5/4 m \quad \text{διατηρεί τις ενέργειες?}$$

"κομψός,"

$$P_1^\mu \cdot P_{2\mu} = P_1^{\mu'} P_{2\mu'} = P_1 \cdot P_2 = \text{αναλογικό Lorentz}$$

$$P_1^\mu \cdot P_{2\mu} = m^2 \left[\frac{5}{4} \cdot \frac{5}{3} + \frac{3}{8} \cdot \frac{4}{3} \right] = m^2 \left[\frac{25}{12} + \frac{6}{12} \right] = -m^2 \frac{19}{12}$$

Ξεπωσ οτι
670 S'

$$P_2^{\mu'} = m(1, 0, 0, 0) \text{ αρα } \rightarrow P_1^{\mu'} \cdot P_{2\mu'} = -m^2 \gamma_{12}$$

$$\gamma_{12} = \frac{19/12}{\sqrt{1 - v_{12}^2}}$$

$$v_{12} = \sqrt{(1 - \gamma^{-2})} \approx 0.78$$

$$P_1 \cdot P_2 \quad P_1^2 \quad P_2^2$$

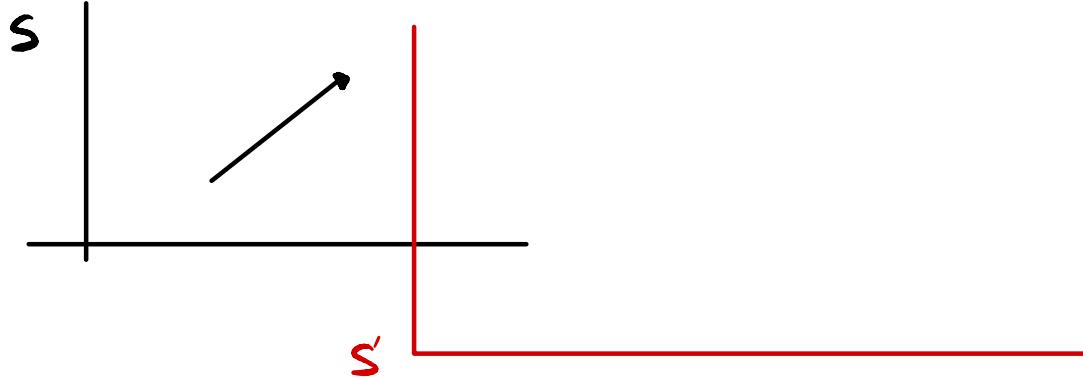
$$\begin{array}{c|c} s & s' \\ \vec{u}_1 & \vec{u}_1' \\ \hline = & (?, ?, 0) \end{array}$$

$$= \left(\frac{3}{10}, \frac{3\sqrt{3}}{10}, 0 \right)$$

"ασχυνός,,

$$\text{μετασχηματισμός } \mathbf{v} = \left(\frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right) \longrightarrow \mathbf{v}' = \left(\frac{dx'}{dt'}, \frac{dy'}{dt'}, \frac{dz'}{dt'} \right)$$

αφού η προσέληνη είναι // \hat{x} λεπίκενος το $v_y' = v_y$;



$$\frac{dx'_1}{dt'_1} = \gamma \frac{(dx_1 - v dt_1)}{(dt_1 - v dx_1)}$$

$$dy'_1 = dy_1, \quad dz'_1 = dz_1,$$

$$\frac{dx'_1}{dt'_1} = \frac{\gamma (dx_1 - v dt_1)}{\gamma (dt_1 - v dx_1)} = \frac{v_{ix} - v}{1 - v_{ix} \cdot v} = \frac{\frac{3}{10} - \frac{4}{5}}{1 - \frac{3}{10} \cdot \frac{4}{5}} = -\frac{25}{38} = u'_{ix}$$

$$\frac{dy'_1}{dt'_1} = \frac{dy_1}{\gamma (dt_1 - v dx_1)} = \frac{v_{iy}/\gamma}{1 - v_{ix} \cdot v} = \frac{\frac{3\sqrt{3}}{10} \cdot \frac{3}{5}}{\frac{38}{50}} = \frac{9\sqrt{3}}{38} = u'_{iy}$$

$$\frac{dz'_1}{dt'_1} = \frac{dz_1}{\gamma (dt_1 - v dx_1)} = \emptyset$$

$$\vec{u}_1 = \left(\frac{3}{10}, \frac{3\sqrt{3}}{10}, 0 \right)$$

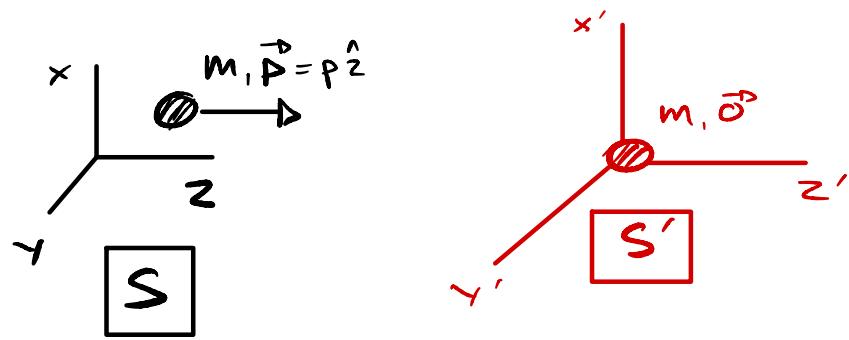
$$\gamma = \frac{5}{3} \quad u_i = \frac{4}{5}$$

S

$$\vec{u}'_1 = \left(-\frac{25}{38}, \frac{9\sqrt{3}}{38}, 0 \right)$$

S'

Πρωτόγονη προς το ευτυχείας
ηρμηνείας συμβολισμού



$$S : P^N = (E, 0, 0, P)$$

$$S' : P^{N'} = (m, 0, 0, 0)$$

$$\vec{v} = \frac{\vec{p}}{E}$$

$$\gamma = \frac{E}{m}$$

$$U = U_x = \frac{P}{E} \quad \gamma = \frac{E}{m}$$

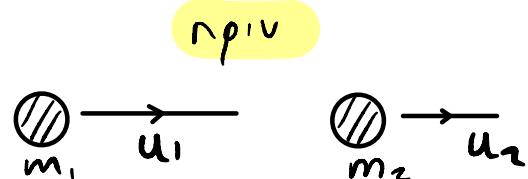
$$\begin{aligned} & \begin{pmatrix} 1 & 0 & 0 & -\gamma u \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma u & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} E \\ 0 \\ 0 \\ P \end{pmatrix} = \begin{pmatrix} \gamma E - \gamma u P \\ 0 \\ 0 \\ -\gamma u E + \gamma P \end{pmatrix} \quad E^2 = P^2 + m^2 \\ & = \begin{pmatrix} \frac{E}{m} \cdot E - \frac{E}{m} \cdot \frac{P}{E} \cdot P \\ 0 \\ 0 \\ -\frac{E}{m} \cdot \frac{P}{E} \cdot E + \frac{E}{m} \cdot P \end{pmatrix} = \begin{pmatrix} \frac{E^2 - P^2}{m} \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} m \\ 0 \\ 0 \\ 0 \end{pmatrix} \end{aligned}$$

Διατηρηση 3-συμμετρίας των Lorentz

εε 1-D σπουδές

κρούση σε 1 διεύθυνση ($\vec{u}_1 \parallel \vec{u}_2 \parallel \vec{u}_3 \parallel \vec{u}_4$)

ερμηνείωση: στην διαφορά των διατάξεων είναι $m_1 = m_2 = m_3 = m_4 = m$. Το ονοματεπώνυμο αναπαύεται.



Κ.Μ. ($\vec{P}_i = m_i \vec{u}_i$)

$$\boxed{S} \quad m_1 u_1 + m_2 u_2 \stackrel{?}{=} m_3 u_3 + m_4 u_4 \quad) \text{ μετ. Lorentz}$$

$$\boxed{S'} \quad m_1 u'_1 + m_2 u'_2 \stackrel{?}{=} m_3 u'_3 + m_4 u'_4$$

$$u' = \frac{u - v}{1 - u \cdot v}$$

$$m_1 \frac{u_1 - v}{1 - u_1 \cdot v} + m_2 \frac{u_2 - v}{1 - u_2 \cdot v} \stackrel{?}{=} m_3 \frac{u_3 - v}{1 - u_3 \cdot v} + m_4 \frac{u_4 - v}{1 - u_4 \cdot v}$$

Σ.Μ. ($\vec{P}_i = \gamma_i m_i \vec{u}_i$)

$$\begin{aligned} P'_i &= \gamma'_i m_i u'_i = \frac{1}{\sqrt{1 - (u'_i)^2}} m_i \frac{u_i - v}{1 - u_i \cdot v} \\ &= \frac{1}{\sqrt{1 - \left(\frac{u_i - v}{1 - u_i \cdot v}\right)^2}} m_i \frac{u_i - v}{1 - u_i \cdot v} \\ &= \frac{1}{\sqrt{\frac{1 - 2u_i \cdot v + u_i^2 v^2 - u_i^2 + v^2 + 2u_i v}{1 - 2u_i \cdot v + u_i^2 v^2}}} m_i \frac{u_i - v}{1 - u_i \cdot v} \\ &= \frac{1 - u_i \cdot v}{\sqrt{(1 - 2u_i \cdot v + u_i^2 v^2 - u_i^2 + v^2 + 2u_i v)^{1/2}}} m_i \frac{u_i - v}{1 - u_i \cdot v} \\ &= \frac{1}{(1 + u_i^2 v^2 - u_i^2 - v^2)^{1/2}} \cdot m_i (u_i - v) \\ &= \underbrace{\frac{1}{\sqrt{1 - u_i^2}}}_{\gamma_i} \underbrace{\frac{1}{\sqrt{1 - v^2}}}_{\gamma} m_i (u_i - v) \\ P'_i &= \gamma_i (\gamma_i m_i u_i - v \gamma_i m_i) \end{aligned}$$

$$\frac{\frac{P_1}{m_1 u_1}}{\sqrt{1-u_1^2}} + \frac{\frac{P_2}{m_2 u_2}}{\sqrt{1-u_2^2}} = \frac{\frac{P_3}{m_3 u_3}}{\sqrt{1-u_3^2}} + \frac{\frac{P_4}{m_4 u_4}}{\sqrt{1-u_4^2}}$$

$$\frac{\frac{m_1 u'_1}{P_1}}{\sqrt{1-u'^2}} + \frac{\frac{m_2 u'_2}{P_2}}{\sqrt{1-u'^2}} = \frac{\frac{m_3 u'_3}{P_3}}{\sqrt{1-u'^2}} + \frac{\frac{m_4 u'_4}{P_4}}{\sqrt{1-u'^2}}$$

↓

$$\gamma(r_1 m_1 u_1 - v \gamma_1 m_1) + \gamma(r_2 m_2 u_2 - v \gamma_2 m_2) = \gamma(r_3 m_3 u_3 - v \gamma_3 m_3) + \gamma(r_4 m_4 u_4 - v \gamma_4 m_4)$$

$$\underbrace{(r_1 m_1 u_1 - v \gamma_1 m_1)}_{\text{P}_1} + \underbrace{(r_2 m_2 u_2 - v \gamma_2 m_2)}_{\text{P}_2} = \underbrace{(r_3 m_3 u_3 - v \gamma_3 m_3)}_{\text{P}_3} + \underbrace{(r_4 m_4 u_4 - v \gamma_4 m_4)}_{\text{P}_4}$$

$$-v \gamma_1 m_1 - v \gamma_2 m_2 = -v \gamma_3 m_3 - v \gamma_4 m_4$$

$$v(\gamma_1 m_1 + \gamma_2 m_2) = v(\gamma_3 m_3 + \gamma_4 m_4)$$

$$v(E_1 + E_2) = v(E_3 + E_4)$$

διαδικασία OTI :

$$\text{Av} \quad P_1 + P_2 = P_3 + P_4 \quad \text{OTI} \quad S$$

$$\text{TOT} \quad P'_1 + P'_2 = P'_3 + P'_4 \quad \text{OTI} \quad S'$$

$$\text{ΕΦΟΓΟΥ} \quad E_1 + E_2 = E_3 + E_4 \quad \text{καν} \quad \vec{P}_i = \gamma_i m \vec{u}_i \quad E_i = \gamma_i m$$

Π.ο ουντόμενη αναδιέξη : χρησιμοποιώ OTI $P'_i = \gamma(P_i - vE)$

$$\underbrace{\gamma(P_1 - vE_1)}_{P'_1} + \underbrace{\gamma(P_2 - vE_2)}_{P'_2} = \underbrace{\gamma(P_3 - vE_3)}_{P'_3} + \underbrace{\gamma(P_4 - vE_4)}_{P'_4}$$

$$(P_1 + P_2) - v(E_1 + E_2) = (P_3 + P_4) - v(E_3 + E_4)$$

για κατά $v \in 0 \leq v < 1$

8 μετ. Γαλιλαίου

κρούση σε 1 διατήξη ($\vec{u}_1 \parallel \vec{u}_2 \parallel \vec{u}_3 \parallel \vec{u}_4$)

S

ηριν

$$m_1 \xrightarrow{\vec{u}_1} m_2 \xrightarrow{\vec{u}_2}$$

μετα

$$m_3 \xrightarrow{\vec{u}_3} m_4 \xrightarrow{\vec{u}_4}$$

5 $m_1 u_1 + m_2 u_2 = m_3 u_3 + m_4 u_4$ (Κ.Ν.)

$$u'_c = u_c - v \quad (\text{μετ. Γαλιλαίου})$$

S' $m_1 u'_1 + m_2 u'_2 = m_3 u'_3 + m_4 u'_4$

$$m_1(u_1 - v) + m_2(u_2 - v) = m_3(u_3 - v) + m_4(u_4 - v)$$

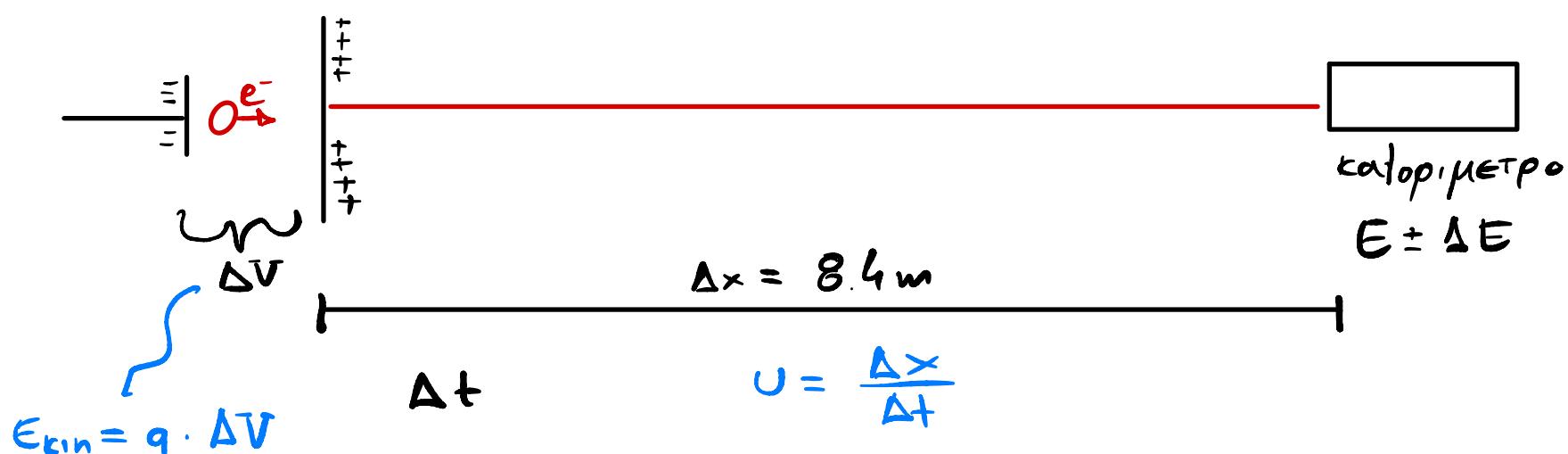
$$m_1 u_1 + m_2 u_2 - v(m_1 + m_2) = m_3 u_3 + m_4 u_4 - v(m_3 + m_4)$$

για να ισχυει ηρεμει $m_1 + m_2 = m_3 + m_4$

Ελεγχός του $\frac{1}{2} m v^2$

W. Bertozzi (1962)

$$E_{\text{kin}}^{\text{rec}} = \frac{1}{2} m v^2 \quad e^- \quad m_{e^-} = 511 \text{ keV}$$



$$E_{\text{kin}} [\text{NeV}]$$

$$0.5$$

$$1.0$$

$$1.5$$

$$4.5$$

$$1.5$$

$$\Delta t [\text{ns}]$$

$$32.3$$

$$30.8$$

$$29.2$$

$$28.4$$

$$28.0$$

$$U \left[10^8 \frac{\text{m}}{\text{s}} \right]$$

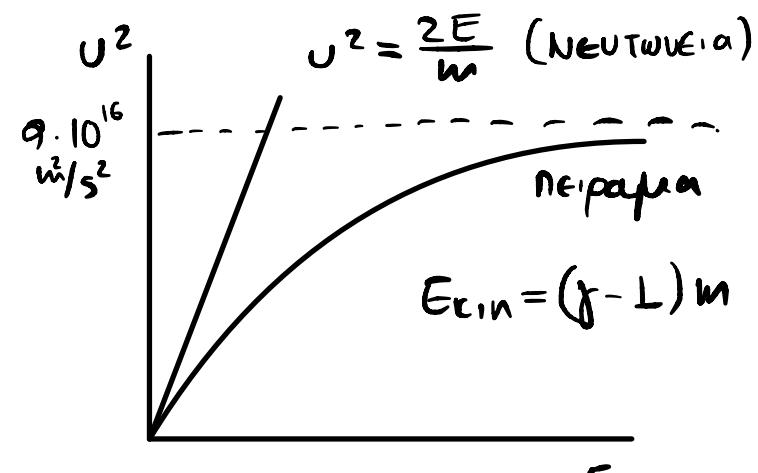
$$2.6$$

$$2.73$$

$$2.88$$

$$2.99$$

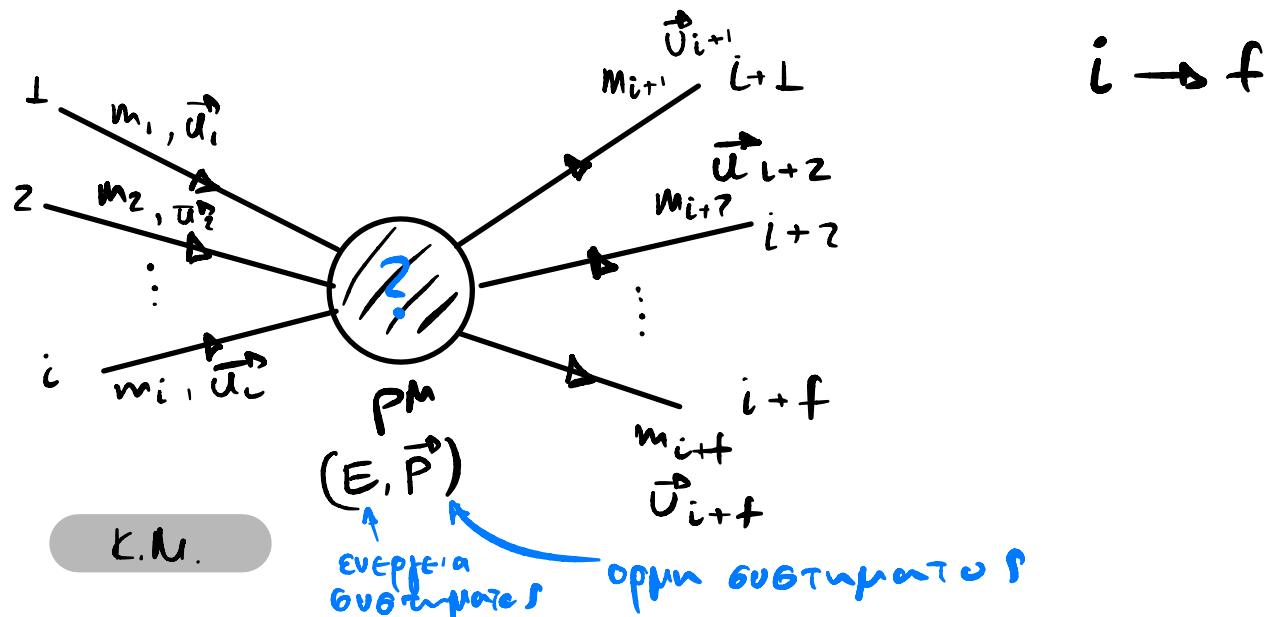
$$3.00$$



$$\stackrel{?}{=} \frac{1}{2} m v^2$$

"youtube Bertozzi
ultimate speed,"

Τετραορημένης συστήματος γερατίδων



$$\begin{cases} m_1 + m_2 + \dots + m_i = m_{i+1} + m_{i+2} + \dots + m_{i+f} \\ m_1 \vec{u}_1 + m_2 \vec{u}_2 + \dots + m_i \vec{u}_i = m_{i+1} \vec{u}_{i+1} + m_{i+2} \vec{u}_{i+2} + \dots + m_{i+f} \vec{u}_{i+f} \end{cases}$$

$$\sum_{n=1}^i m_n = \sum_{n=i+1}^{i+f} m_n \quad (\text{L Eξ.})$$

$$\sum_{n=1}^i m_n \vec{u}_n = \sum_{n=i+1}^{i+f} m_n \vec{u}_n \quad (\text{B Eξ.})$$

ΣM

$$\sum_{n=1}^i P_n^M = \sum_{n=i+1}^{i+f} P_n^M = P^M = P_{cm}^M \quad (\text{L Eξ.})$$

$$\begin{cases} \sum_{n=1}^i \cancel{P_n} = \sum_{n=i+1}^{i+f} \cancel{P_n} \\ \sum_{n=1}^i \cancel{P_n} m_n \vec{u}_n = \sum_{n=i+1}^{i+f} \cancel{P_n} m_n \vec{u}_n \end{cases}$$

H συνολική τετραορημένη ενσώ κλειστού συστήματος είναι οτανδερη

$$P^M = \sum_n P_n^M = (E, \vec{P})$$

$$M = \text{ωνήσιμη μάζα συστήματος} = \sqrt{s} = \sqrt{E^2 - (\vec{P})^2}$$

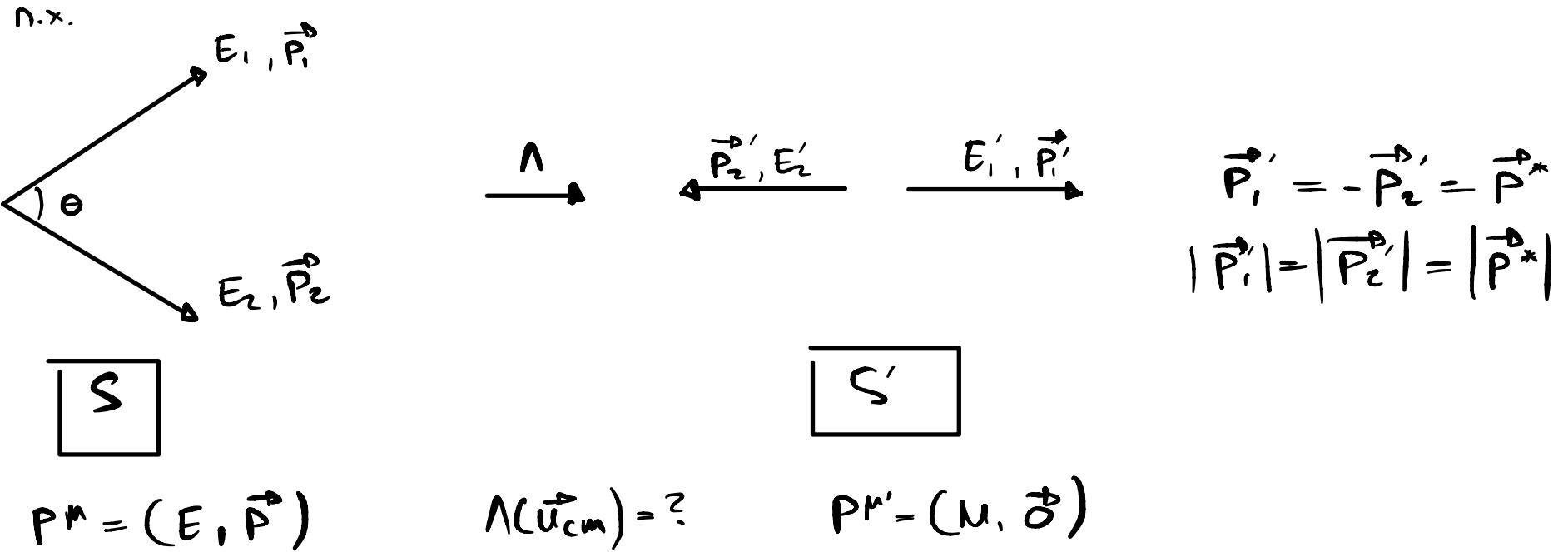
n.x. example $2 \rightarrow 2$

$$M \neq m_1 + m_2$$

Συγτηρακτικά κέντρου oppins (κέντρο μάζας) $\vec{P} = 0$

$$P_{cm}^M \equiv P^M = (E, \vec{P}) \xrightarrow{\wedge} P^M = (M, \vec{0})$$

Βοηθεί να σκεφτούμε το P^M και να υποθέτουμε γερατίδιο "CM," το οποίο "καρβαλεῖ," την ενέργεια & oppin οποκύπρου του συστήματος



$$\vec{v}_{cm} = \frac{\vec{p}}{E} = \frac{\vec{p}_1 + \vec{p}_2}{E_1 + E_2}$$

$$\gamma = \frac{E}{N} = \frac{E_1 + E_2}{\sqrt{(E_1 + E_2)^2 - (\vec{p}_1 + \vec{p}_2)^2}}$$

Masa sustractora 2γ

* $\vec{p}_1 = (3, 4, 0)$ [Gev] Masa sustractora ?

* $\vec{p}_2 = (3, -4, 0)$ [Gev]

$N = \begin{cases} 0 \\ > 0 \\ \text{exigencia} \end{cases}$ $(A) \\ (B) \\ (C)$

S $E_i^2 = m_i^2 + (\vec{p}_i)^2$

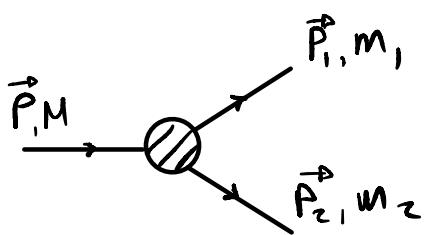
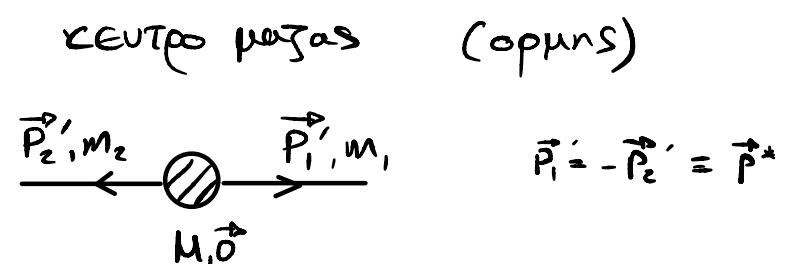
$$P_1^{\mu} = (E_1, \vec{p}_1) = (5, 3, 4, 0)$$

$$P_2^{\mu} = (E_2, \vec{p}_2) = (5, 3, -4, 0)$$

$$P^{\mu} = (E_1 + E_2, \vec{p}_1 + \vec{p}_2) = (10, 6, 0, 0)$$

$$P^{\mu} P_{\mu} = -N^2 = -10^2 + 6^2 = 64 \quad [\text{Gev}]$$

$$N = 8 \quad [\text{Gev}]$$

$M \rightarrow m_1, m_2$  S  S'

$P^r = p_1^r + p_2^r$

 S

$P^{r'} = p_1^{r'} + p_2^{r'}$

 S' $\alpha/\bar{\alpha}$ $\sigma_{\mu\omega S}$

$P^r \neq P^{r'} = \Lambda_r^r P^r$

$(P^r)^2 = (P^{r'})^2$

Π.χ.

$P^r = (E, \vec{p})$
 $P_1^r = (E_1, \vec{p}_1)$
 $P_2^r = (E_2, \vec{p}_2)$

 S

$P^{r'} = (M, \vec{0})$
 $P_1^{r'} = (E_1^*, \vec{p}^*)$
 $P_2^{r'} = (E_2^*, -\vec{p}^*)$

 S'

$P^r \neq P^{r'} + P_2^r$

$s = M^2 = (E_1 + E_2)^2 - (\vec{p}_1 + \vec{p}_2)^2$

$\sqrt{s} = M$

$(P')^2 = (P_1 + P_2)^2$

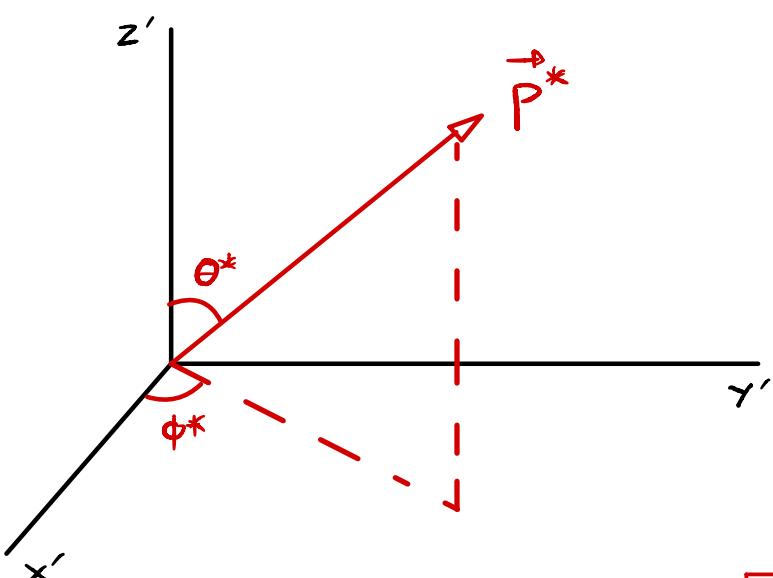
αναλογία Lorentz

Βαρύοι ελευθερίας για K.D. για δεδομένα M, m_1, m_2 ;

$P^r = p_1^r + p_2^r \longrightarrow$

$$\begin{array}{l} 3 \times 4 = 12 \text{ παραμετροί} \\ - 4 \text{ εξιγωνείς (δεσμοί)} \\ - 4 \text{ } P^r \text{ γνωστό για K.D.} \\ - 2 \text{ } p_i^2 = m_i^2 \quad p_2^2 = m_2^2 \quad (+---) \end{array}$$

2 βαρύοι ελευθερίας

 θ^*, ϕ^*

$P' = (M, \vec{0})$
 $P'_1 = (E_1^*, \vec{p}^*)$
 $P'_2 = (E_2^*, -\vec{p}^*)$

$\vec{p}^* = (p^* \sin \theta^* \cos \phi^*, p^* \sin \theta^* \sin \phi^*, p^* \cos \theta^*)$

πηλρώσ
προσδιορισμό μα
ευαρτησει
των μαζων

$E_1^* = \frac{M^2 + m_1^2 - m_2^2}{2M}, \quad E_2^* = \frac{M^2 + m_2^2 - m_1^2}{2M}$

$|\vec{p}_{1,2}^*|^2 = \frac{[M^2 - (m_1 - m_2)^2][M^2 - (m_1 + m_2)^2]}{4M^2} = |\vec{p}^*|^2$

$$\Theta^* = \phi^* = 0$$

$$P^r = (n, 0, 0, 0)$$

$$P_1^r = (E_1^*, 0, 0, P^*)$$

$$P_2^r = (E_2^*, 0, 0, -P^*)$$

$$P' = P_1' + P_2' \rightarrow (P' - P_1')^2 = (P_2')^2$$

(+) ---

$$(P')^2 + (P_1')^2 - 2P' \cdot P_1' = m_2^2$$

$$M^2 + m_1^2 - 2ME_1^* = m_2^2$$

$$E_1^* = \frac{M^2 + m_1^2 - m_2^2}{2M}$$

opposite

$$E_2^* = \frac{M^2 + m_2^2 - m_1^2}{2M}$$

$$\vec{P}_1^* = \vec{P}^*$$

$$(E_1^*)^2 = m_1^2 + |\vec{P}_1^*|^2 = m_1^2 + (P^*)^2$$

$$P = |\vec{P}|$$

$$(P^*)^2 = (E_1^*)^2 - m_1^2 = (E_2^*)^2 - m_2^2$$

$$A = m_1 - m_2$$

$$B = m_1 + m_2$$

$$A^2 + B^2 = (m_1^2 + m_2^2) / 2$$

$$4M^2 (P^*)^2 = (M^2 + (m_1 - m_2)(m_1 + m_2))^2 - m_1^2 4M^2 \quad (1)$$

$$= (M^2 - (m_1 - m_2)(m_1 + m_2))^2 - m_2^2 4M^2 \quad (2)$$

$$(1) \rightarrow = M^4 + (A \cdot B)^2 + 2A \cdot B M^2 - m_1^2 4M^2$$

$$(2) \rightarrow = M^4 + (A \cdot B)^2 - 2A \cdot B M^2 - m_2^2 4M^2$$

$$\frac{1}{2}((1)+(2)) = M^4 + (A \cdot B)^2 - 2(m_1^2 + m_2^2)M^2$$

$$= M^4 + (A \cdot B)^2 - (A^2 + B^2) M^2$$

$$= M^2(M^2 - A^2) - B^2(M^2 - A^2)$$

$$4M^2 (P^*)^2 = (M^2 - B^2)(M^2 - A^2)$$

$$(P^*)^2 = |\vec{P}_{1,2}^*|^2 = \frac{[M^2 - (m_1 - m_2)^2][M^2 - (m_1 + m_2)^2]}{4M^2}$$

2 → 1

opposite $\mu^- e^- \tau \nu \tau$

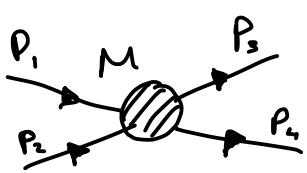
1 → 2

$$P^r = P_1^r + P_2^r \quad 1 \rightarrow 2$$

$$P_1^r + P_2^r = P^r \quad 2 \rightarrow 1$$

2 → 2

$$[m_1 + m_2 \xrightarrow{M} m_3 + m_4]$$



εφετομαστε το 2 → 2 σων 2 → 1 και 1 → 2 με ευδιαγρεση
"κατασταση" (M, \vec{P})

$P = (M, \vec{P})$ πλα $\vec{P} = 0$: κεντρο μαζας (μηδενικη ορικη όψη)

$$P_1 + P_2 = P_3 + P_4$$

$$E_1^* = \frac{M^2 + m_1^2 - m_2^2}{2M}, \quad E_2^* = \frac{M^2 + m_2^2 - m_1^2}{2M}$$

$$|\vec{P}_{1,2}^*|^2 = \frac{[M^2 - (m_1 - m_2)^2][M^2 - (m_1 + m_2)^2]}{4M^2}$$

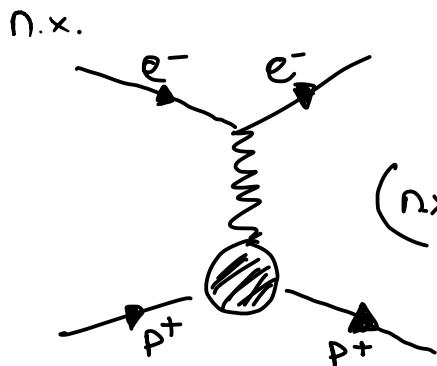
για την τελικη κατασταση (p_3, p_4)
αντικαθιστουμε (1,2) → (3,4)
D.X.

$$E_3^* = \frac{M^2 + m_3^2 - m_4^2}{2M}, \quad |\vec{P}_{3,4}^*| = \frac{[M^2 - (m_3 - m_4)^2][M^2 - (m_3 + m_4)^2]}{2M}$$

ελαστικη ερωγη

Νευτωνια : $T_{\text{νριν}} = T_{\text{μετα}}$ {θερμοτητα, νχος, τριβης}

Σχετικικικα : $m_1, m_2, \dots, m_n \rightarrow m_1, m_2, \dots, m_n$ {ιδιες μαζες νριν+μετα}



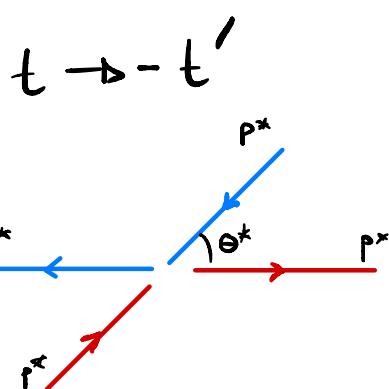
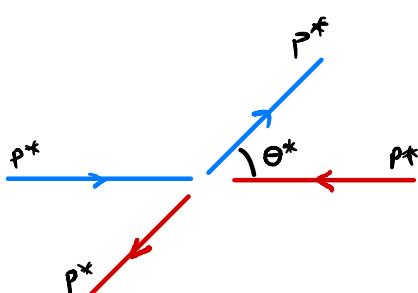
S*

$$E_1^* = E_3^*, \quad E_2^* = E_4^*$$

$$|\vec{P}_{1,2}^*| = |\vec{P}_{3,4}^*| = |\vec{P}^*|$$

$$m_1 = m_3 \quad \text{και} \quad m_2 = m_4$$

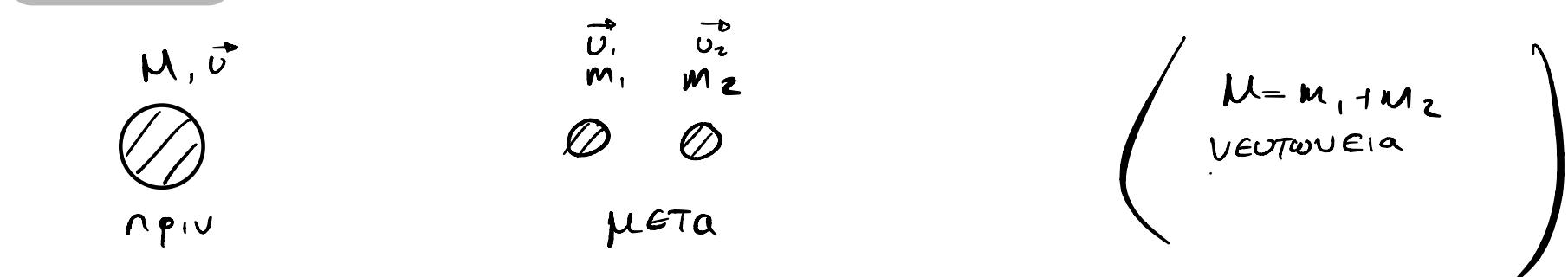
C.M



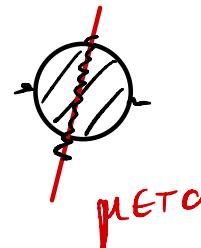
ευηλετρια
αντιστροφης
χρονου
ανατει οτι
 $|\vec{p}_1^*| = |\vec{p}_2^*| = |\vec{p}_3^*| = |\vec{p}_4^*| = p^*$

Παραδειγματα αντιδρασεων

$1 \rightarrow 2$



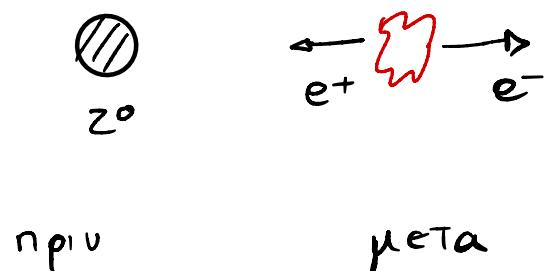
NEUTRINIA STO K.O.
n₁ u₁
n₂ u₂
META



Τα δύο κοριτσιά
παρασκευούν
αγιάντα σιότι
 $M = m_1 + m_2$

$$Z^0 \rightarrow e^- e^+ \quad m_Z = 91 \text{ GeV} \quad m_{e^-} = m_{e^+} = 511 \text{ keV}$$

$$m_Z/m_e \approx 178$$



μαζα των προϊοντων
μικροτερην της
αρχικης!

$$M > m_{e^-} m_{e^+}$$

Τα e^\pm εχουν
μεγαλυτερη ταχυτητα
αρχικη και στο K.O.

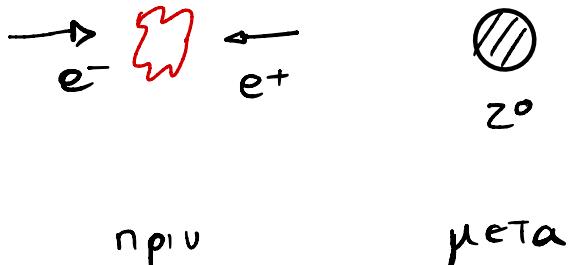
$$P^* \approx M/2$$

Μπορει η αντιτελιδραση να έχει χώρα με την αυτιδετη χρονικη
σειρα τ_2 αντιτελιδρασην να έχει χώρα με την αυτιδετη χρονικη

T: { Συμμετρια αντιστροφης χρονου }

~ διατηρηση
της ενέργειας
(Noether)

$2 \rightarrow 1$



Συμμετρια αντιστροφης χρονου

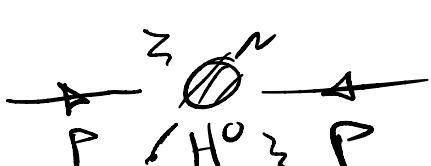
$$m_{e^-} + m_{e^+} \leq M_Z$$

μαζα του προϊοντος ειναι μεγαλυτερη
της αρχικης!

CERN

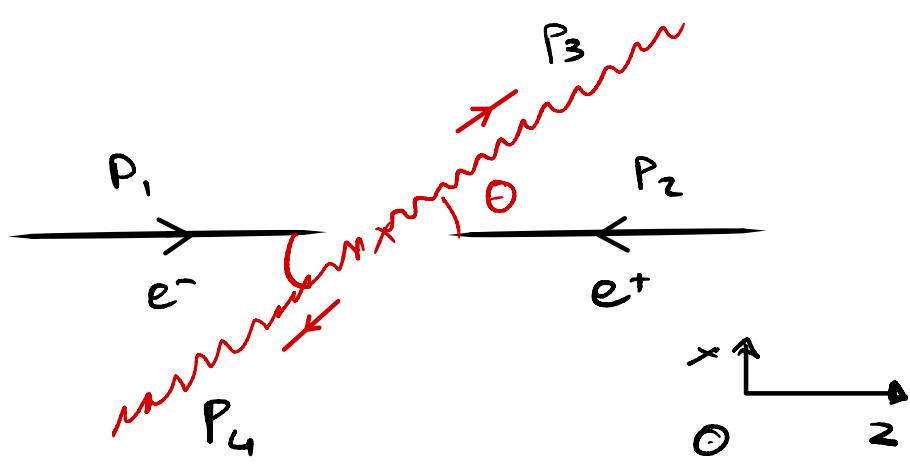
$$pp \rightarrow H^0 + \dots$$

Higgs boson



Large Hadron Collider

Eγawλωση $e^-e^+ \rightarrow 2\gamma$



$$m_{e^+} + m_{e^-} \rightarrow 0 + 0 !$$

η μάρα των επικέρους γεγονότων
δεν διατηρείται πριν // μετά

η αναλογία μάρα του γεγονούτος ?

$$E_\gamma^{\min} = ?$$

$$P_1 = (\sqrt{m_e^2 + p^2}, 0, 0, p)$$

$$P_2 = (\sqrt{m_e^2 + p^2}, 0, 0, -p)$$

$$P_3 = (E_\gamma, 0, E_\gamma \sin \theta, E_\gamma \cos \theta)$$

$$P_4 = (E_\gamma, 0, -E_\gamma \sin \theta, -E_\gamma \cos \theta)$$

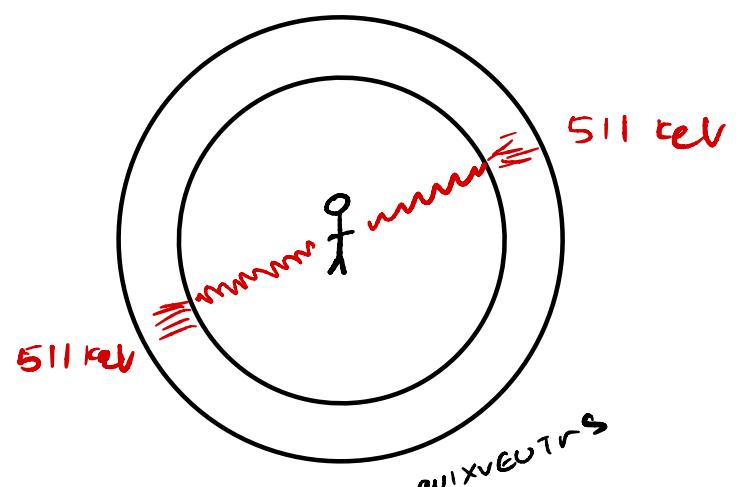
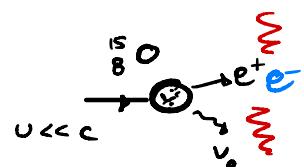
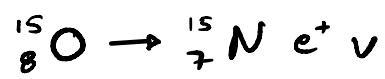
$$E_\gamma = \sqrt{m_e^2 + p^2}$$

$$E_\gamma^{\min} = m_e = 511 \text{ keV}$$

για $p \rightarrow 0$

Positron Emission Tomography

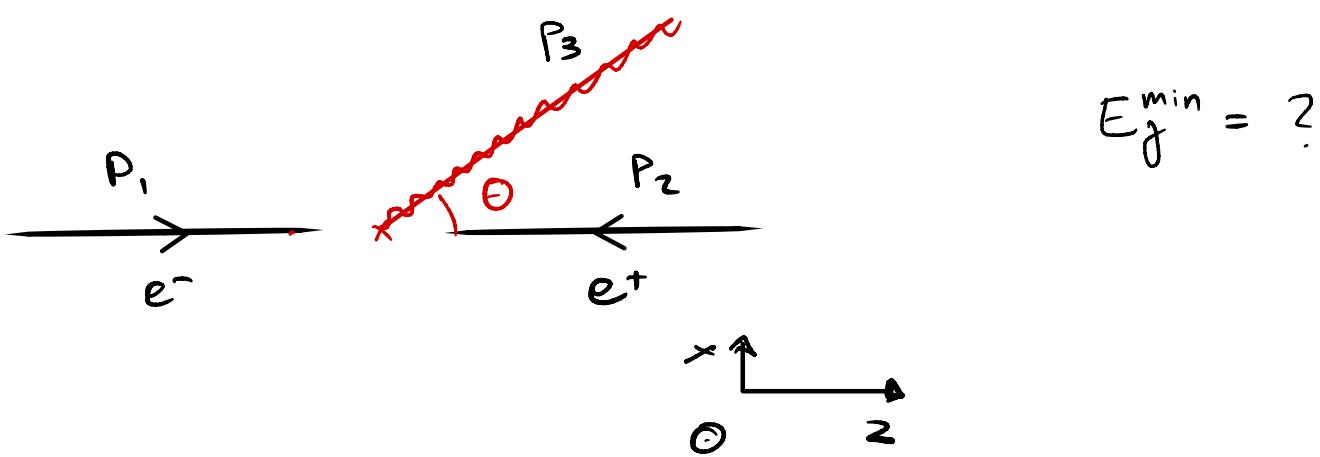
ραδιοφαρμακό



$$\Delta\phi \approx \pi$$

$$\Delta t \leq 0.5 \text{ ns}$$

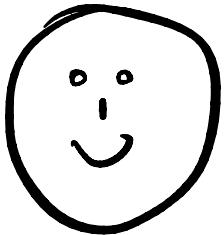
$E \xi \omega$ | wBN $e^-e^+ \rightarrow \gamma$



$$E_\gamma^{\min} = ?$$

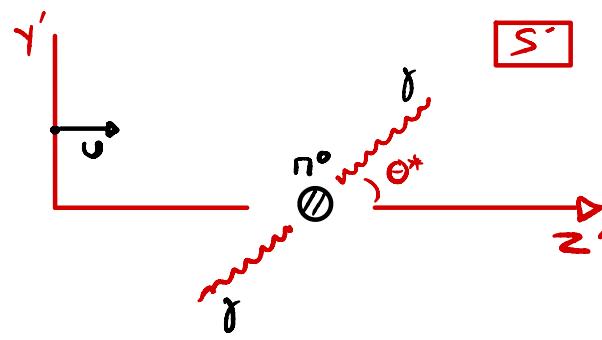
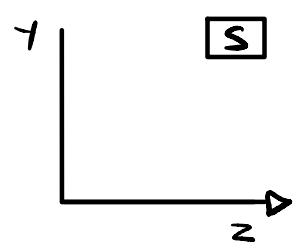
$$\begin{aligned} P_1 &= (\sqrt{m_e^2 + p^2}, 0, 0, p) & P_3 &= (E_\gamma, 0, E_\gamma \sin\theta, E_\gamma \cos\theta) \\ P_2 &= (\sqrt{m_e^2 + p^2}, 0, 0, -p) & P_4 &= (0, 0, 0, 0) \end{aligned}$$

$$P_1 + P_2 \stackrel{?}{=} P_3 + P_4$$



$$E'_\gamma = E_\gamma^* = m/c^2$$

нропрнрн 2 (2021)



$\Lambda(-v)$

$$\begin{bmatrix} \gamma & 0 & 0 & \gamma v \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \gamma v & 0 & 0 & \gamma \end{bmatrix}$$

$$m \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$= \frac{m}{2} \begin{bmatrix} 1 \\ \sin\theta^* \\ 0 \\ \cos\theta^* \end{bmatrix} + \frac{m}{2} \begin{bmatrix} 1 \\ -\sin\theta^* \\ 0 \\ -\cos\theta^* \end{bmatrix}$$

S'

$$\begin{bmatrix} \gamma & 0 & 0 & \gamma v \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \gamma v & 0 & 0 & \gamma \end{bmatrix}$$

$$\frac{m}{2} \begin{bmatrix} 1 \\ \sin\theta^* \\ 0 \\ \cos\theta^* \end{bmatrix}$$

$$= \begin{bmatrix} \frac{m}{2}(1+vcos\theta^*) \\ \frac{m}{2}\sin\theta^* \\ 0 \\ \frac{m}{2}(v+\cos\theta^*) \end{bmatrix} = E \begin{bmatrix} 1 \\ \sin\theta \\ 0 \\ \cos\theta \end{bmatrix}$$

$$E = \frac{m}{2}(1+vcos\theta^*)$$

$$\sin\theta = \frac{\sin\theta^*}{\gamma(1+vcos\theta^*)}$$

$$\cos\theta = \frac{v+cos\theta^*}{1+vcos\theta^*}$$

$$f = \gamma(1+vcos\theta^*) f^*$$

Doppler

$$\theta^* = 0$$

$$f = \sqrt{\frac{1+v}{1-v}} f^*$$

$$\theta = 0$$



$$\theta^* = \frac{\pi}{2}$$

$$f = \gamma f^* \text{ Blue shift}$$

$$\cos\theta = v$$

суперима бтov
авиасен та
актива пк $\theta^* = \frac{\pi}{2}$
гто S'

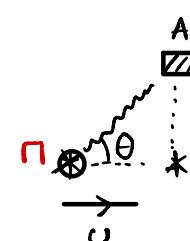
$$\theta = \frac{\pi}{2} \Rightarrow \cos\theta^* = -v$$

$$f = \gamma(1-v^2) f^* = \sqrt{1-v^2} f^*$$

$$f = f^* / \gamma \text{ red shift}$$

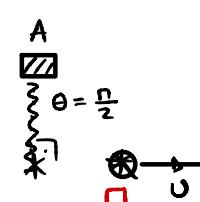
суперима бтov
авиасен та
актива пк $\theta = \frac{\pi}{2}$
гто S

#1

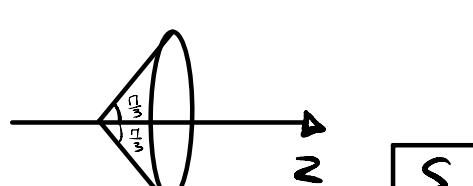
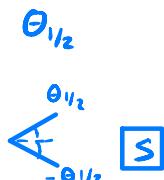


Линия Авиасен

#2



$\theta^* = \pm \frac{\pi}{2}$
актив бтov
 S'



$$\sin\theta_{1/2} = \frac{1}{\gamma}$$

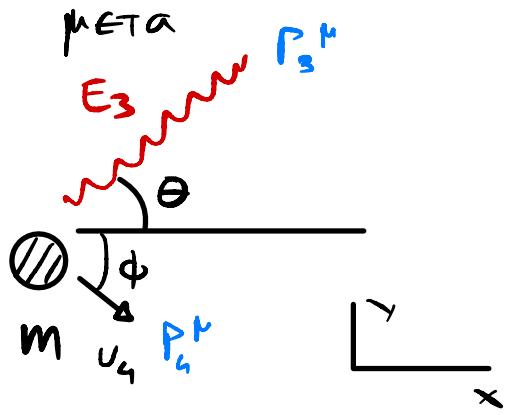
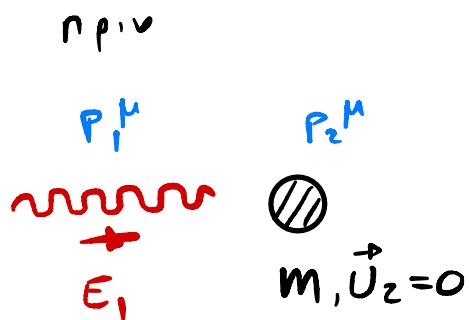
$$\tan(\theta_{1/2}) = (\gamma v)^{-1}$$

$$\cos\theta_{1/2} = v$$

$$\text{n.r. фла } v = \frac{1}{2}$$

$$\theta_{1/2} = 60^\circ$$

Greek Compton



$$\begin{aligned} m &= \gamma v w G T o \\ \gamma \cdot a & E_1 = \gamma v w G T o \\ E_3 &= E_3(\theta, E_1) = ? \\ \lambda_3 &= \lambda_3(\theta, \lambda_1) = ? \\ E &= h \nu = h \frac{c}{\lambda} \\ v \cdot \lambda &= c \end{aligned}$$

$$P_1^\mu + P_2^\mu = P_3^\mu + P_4^\mu$$

$$\begin{bmatrix} E_1 \\ E_1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} m \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} E_3 \\ E_3 \cos \theta \\ E_3 \sin \theta \\ 0 \end{bmatrix} + \begin{bmatrix} E_4 \\ P_4 \cos \phi \\ -P_4 \sin \phi \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} E_1 \\ E_1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} m \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} E_3 \\ E_3 \cos \theta \\ E_3 \sin \theta \\ 0 \end{bmatrix} = \begin{bmatrix} E_4 \\ P_4 \cos \phi \\ -P_4 \sin \phi \\ 0 \end{bmatrix}$$

$$(P_1^\mu + P_2^\mu - P_3^\mu)^2 = (P_4^\mu)^2$$

$$(P_1^\mu)^2 + (P_2^\mu)^2 + (P_3^\mu)^2 + 2P_1^\mu P_{2\mu} - 2P_1^\mu P_{3\mu} - 2P_2^\mu P_{3\mu} = m^2$$

$$\begin{aligned} (- & + + +) \rightarrow P^2 = -m^2 \\ (+ & - - -) \rightarrow \\ (P^\mu)^2 &= m^2 \rightarrow \\ P_1^\mu \cdot P_{2\mu} &= E_1 \cdot E_2 - \vec{P}_1 \cdot \vec{P}_2 \end{aligned}$$

$$0 + m^2 + 0 + 2E_1 m - 2(E_1 E_3 - E_1 E_3 \cos \theta) - 2m E_3 = m^2$$

$$\frac{1}{m E_1 E_3} (E_1 m - E_1 E_3 (1 - \cos \theta) - m E_3) = 0$$

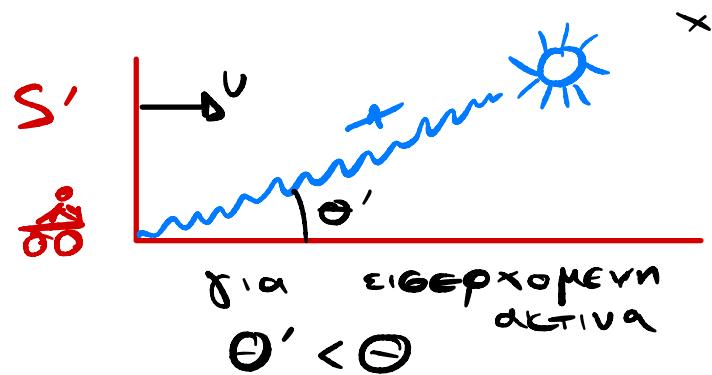
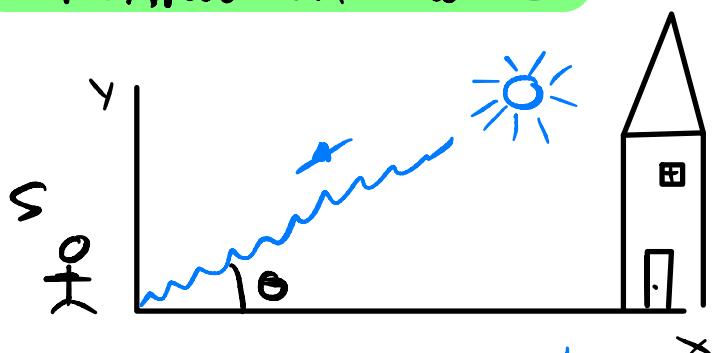
$$\frac{1}{E_3} - \frac{1}{m} (1 - \cos \theta) - \frac{1}{E_1} = 0$$

$$\lambda_3 = \lambda_1 + \frac{hc}{m} (1 - \cos \theta)$$

$$\begin{aligned} \lambda_c &= \frac{hc}{m} = \text{μνκος κυριατος Compton} \\ &= \text{μνκος κυριατος ενας φωτονιου ενεργειας } E = m \end{aligned}$$

μνα ενα πρωτονιο $\lambda_c \approx 1.5 \text{ fm}$

Anomalien Φ_{WTO3}



$$E \begin{bmatrix} 1 \\ -\cos\theta \\ -\sin\theta \\ 0 \end{bmatrix} = P^M$$

$$E' \begin{bmatrix} 1 \\ -\cos\theta' \\ -\sin\theta' \\ 0 \end{bmatrix} = P^{M'}$$

$$E' \begin{bmatrix} 1 \\ -\cos\theta' \\ -\sin\theta' \\ 0 \end{bmatrix} = \begin{bmatrix} r & -ru & 0 & 0 \\ -ru & r & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} E \begin{bmatrix} 1 \\ -\cos\theta \\ -\sin\theta \\ 0 \end{bmatrix}$$

$$|\vec{P}'| = E' = \gamma E + \rho u E \cos\theta = \gamma E (1 + u \cos\theta)$$

$$P_x' = -E' \cos\theta' = -\rho u E - \rho E \cos\theta = -\gamma E (u + \cos\theta)$$

$$P_y' = -E' \sin\theta' = -E \sin\theta$$

$$P_z' = 0 = 0$$

$$\tan\theta' = \frac{\sin\theta}{r(u + \cos\theta)}$$

$$\sin\theta' = \frac{\sin\theta}{\gamma(1 + u \cos\theta)} = P_y'/E'$$

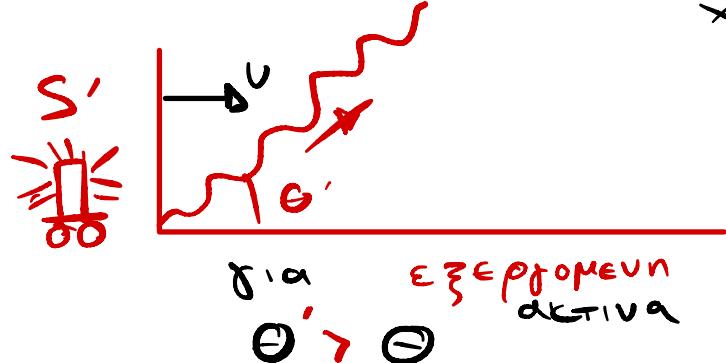
$$\cos\theta' = \frac{u + \cos\theta}{1 + u \cos\theta}$$

$$\boxed{\tan\frac{x}{2} = \frac{\sin x}{1 + \cos x}}$$



$$\tan(\theta'/2) = \sqrt{\frac{1-u}{1+u}}$$

$\tan\theta'/2$ είναι πυργίως αντουρα $0 \leq \theta \leq \pi/2$



$$E \begin{bmatrix} 1 \\ +\cos\theta \\ +\sin\theta \\ 0 \end{bmatrix} = P^M$$

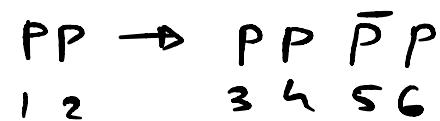
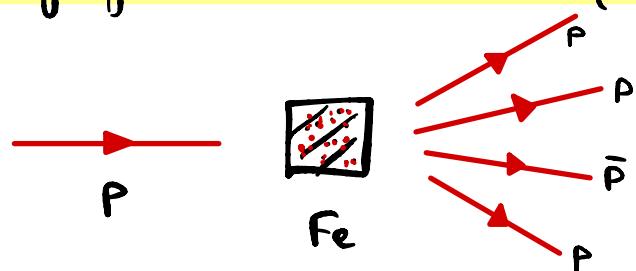
$$E' \begin{bmatrix} 1 \\ +\cos\theta' \\ +\sin\theta' \\ 0 \end{bmatrix} = P^{M'}$$

$$E \begin{bmatrix} 1 \\ \cos\theta \\ \sin\theta \\ 0 \end{bmatrix} = \begin{bmatrix} r & ru & 0 & 0 \\ ru & r & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} E' \begin{bmatrix} 1 \\ +\cos\theta' \\ +\sin\theta' \\ 0 \end{bmatrix}$$

Ενέργεια κατωφλίου

παραγωγή ενεργειακού - πρωτονίου

S



(+ ---)

$$p_1^{\mu} + p_2^{\mu} = p_3^{\mu} + p_4^{\mu} + p_5^{\mu} + p_6^{\mu}$$

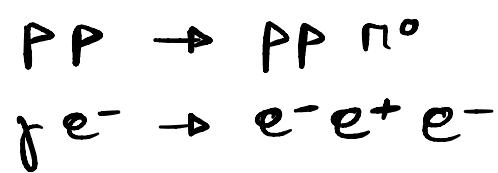
$$\left(\left(\frac{E_1}{\vec{p}_1} \right) + \left(\frac{m}{\vec{0}} \right) \right)^2 = \left(p_3^{\mu} + p_4^{\mu} + p_5^{\mu} + p_6^{\mu} \right)^2$$

$$m^2 + m^2 + 2(E_{1,m}^{\min} - \vec{p}_1 \cdot \vec{0}) = \left(\left(\frac{m}{0} \right) + \left(\frac{m}{0} \right) + \left(\frac{m}{0} \right) + \left(\frac{m}{0} \right) \right)^2_{K_0}$$

$$E_{1,m}^{\min} = ? = (4m)^2$$

$$2m^2 + 2E_{1,m}^{\min} = 16m^2$$

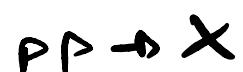
$$E_{1,m}^{\min} = 7m \approx 7 \text{ GeV}$$



εαν ξουμε

$$\begin{array}{c} \xrightarrow{\text{ηπωτονίο}} \\ (E, \vec{p}) \end{array} \quad \left\{ \begin{array}{c} X \\ \perp \end{array} \right. \quad \begin{array}{c} \xleftarrow{\text{ηπωτονίο}} \\ (E, -\vec{p}) \end{array} \quad \left\{ \begin{array}{c} Z \\ \perp \end{array} \right.$$

$$2E^{\min} = M_X$$



$$n \times \text{Γ.Α. } X = p p \bar{p} \bar{p} \quad E^{\min} = 2 \text{ GeV}$$

$$p_1^{\mu} + p_2^{\mu} = (2E, \vec{p} - \vec{p}) = (fs, \vec{0})$$

- (1) $\bar{\nabla} \cdot \bar{E} = \rho / \epsilon_0$
 (2) $\bar{\nabla} \cdot \bar{B} = 0$
 (3) $\bar{\nabla} \times \bar{E} + \frac{\partial \bar{B}}{\partial t} = 0$
 (4) $\bar{\nabla} \times \bar{B} - \mu_0 \epsilon_0 \frac{\partial \bar{E}}{\partial t} = \mu_0 \bar{J}$

αντοιωτες σε μετ. Lorentz

* εξισώση γενεκειας

* προβλήματα H/M κυριών στο κενό

$$\bar{\nabla} = (\partial_x, \partial_y, \partial_z)$$

$$\vec{F}_L = q(\bar{E} + \bar{v} \times \bar{B}) \leftarrow \text{δυναμ. Lorentz}$$

$$\bar{\nabla}(4) \rightarrow \bar{\nabla} \left(\bar{\nabla} \times \bar{B} \underset{\uparrow}{-} \mu_0 \epsilon_0 \frac{\partial \bar{E}}{\partial t} \right) = \bar{\nabla} \left(\mu_0 \bar{J} \underset{\uparrow}{\text{(↓)}} \right)$$

$$-\mu_0 \epsilon_0 \frac{\partial \bar{\nabla} \bar{E}}{\partial t} = \mu_0 \bar{\nabla} \bar{J}$$

$$-\mu_0 \epsilon_0 \frac{\partial (\rho / \epsilon_0)}{\partial t} = \mu_0 \bar{\nabla} \bar{J}$$

* $\frac{\partial \rho}{\partial t} + \bar{\nabla} \bar{J} = 0$

εξ. γενεκειας
τοπικη διατηρηση του ηλ. φορτιου

$$\bar{\nabla} \times (4) \quad \bar{\nabla} \times \left(\bar{\nabla} \times \bar{B} \underset{\uparrow}{-} \mu_0 \epsilon_0 \frac{\partial \bar{E}}{\partial t} \right) = \mu_0 \bar{J} = 0 \quad \text{στο κενό } \rho=0 \quad \bar{J}=0$$

$$\bar{\nabla} \times (\bar{\nabla} \times \bar{B}) = -\nabla^2 \bar{B} - \mu_0 \epsilon_0 \frac{\partial (\bar{\nabla} \times \bar{E})}{\partial t} = -\nabla^2 \bar{B} - \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left(-\frac{\partial \bar{B}}{\partial t} \right) = 0$$

$\bar{A} \times (\bar{B} \times \bar{C}) = \bar{B}(\bar{A} \bar{C}) - \bar{C}(\bar{A} \bar{B})$ ταυτοτητα

$\bar{\nabla} \times (\bar{\nabla} \times \bar{B}) = \bar{\nabla}(\bar{\nabla} \bar{B}) - \nabla^2 \bar{B}$

$\bar{\nabla} \bar{B} = 0$

* $\nabla^2 \bar{B} - \frac{1}{c^2} \frac{\partial^2 \bar{B}}{\partial t^2} = 0$

$\nabla^2 \bar{E} - \frac{1}{c^2} \frac{\partial^2 \bar{E}}{\partial t^2} = 0$

οψιως $\nabla \times (3)$

οριζουτας ως $c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} \stackrel{SI}{=} 3 \cdot 10^8 \text{ m/s}$

$\square \bar{B} = 0$
 $\square \bar{E} = 0$

$c = 1$ ευρισκη

Δυνατή Minkowski & ταυτότητα H/M πεδίου

$$K^{\mu} = \frac{dP^{\mu}}{dT} = \frac{d}{dT}(mU^{\mu}) = m\dot{U}^{\mu} = q F^{\mu\nu} U_{\nu}$$

ούτως
 $\frac{dM}{dT} = 0$

↑
ταυτότητας δυνατής
ταυτότητας H/M πεδίου

προβλημάτες για K^{μ}

$$K^{\mu} \sim q$$

$$K^{\mu} \sim \bar{E}, \bar{B}$$

$$K^{\mu} \sim U^{\mu}$$

$$\left[\Lambda^{\mu}_{\nu} \right] = \begin{bmatrix} 0 & -\gamma^0 & 0 & 0 \\ -\gamma^0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

αυτοφοιτώσας ταυτότητας \perp ταξέως

$$dx^{\mu} = (dt, d\vec{x})$$

↑
Νέα άποψη 3-ανύδρα

$$dx^{\mu} = \Lambda^{\mu}_{\nu} dx^{\nu}$$

προβλημάτες για $F^{\mu\nu}$

$$\bullet F^{\mu'\nu'} = \Lambda^{\mu'}_{\mu} \Lambda^{\nu'}_{\nu} F^{\mu\nu} \quad (\text{ισχυει για ταυτότητα } z \cong \text{ ταξέως})$$

$$(\Delta x^{\mu'} = \Lambda^{\mu'}_{\mu} \Delta x^{\mu})$$

$$\bullet K^{\mu} U_{\mu} = \frac{d}{dT}(mU^{\mu}) U_{\mu} = \frac{1}{2} \frac{d}{dT}(mU^{\mu} U_{\mu}) = 0$$

$$U^{\mu} \cdot U_{\mu} = -1$$

$$K^{\mu} \cdot U_{\mu} = (q F^{\mu\nu} U_{\nu}) U_{\mu} \quad \begin{array}{l} \text{Βουβοι δεικτές} \\ \text{ηρεμει} \end{array} = 0 \quad (\perp)$$

$$= q F^{\nu\mu} U_{\mu} U_{\nu} = 0 \quad (z)$$

$$U_{\mu} U_{\nu} = U_{\nu} U_{\mu}$$

$$(\perp) + (z) \quad q(F^{\mu\nu} + F^{\nu\mu}) U_{\mu} U_{\nu} = 0$$

$$F^{\mu\nu} = -F^{\nu\mu} \quad \leftarrow \text{αντισυμμετρικός}$$

$$F^{\mu\mu} = 0$$

γενικότερη δυνατή μορφή

αντισυμμετρικού ταυτότητας

\perp ταξέως

6 ανεξάρτητες συνιστώσεις
(βαρύ, ελεύθερος)

$$F^{\mu\nu} = \begin{bmatrix} 0 & F^{01} & F^{02} & F^{03} \\ -F^{01} & 0 & F^{12} & F^{13} \\ -F^{02} & -F^{12} & 0 & F^{23} \\ -F^{03} & -F^{13} & -F^{23} & 0 \end{bmatrix}$$

↑
polar
 \vec{E}
axisial
 \vec{B}
 $\mu = 0$
 $\mu = 1$
 $\mu = 2$
 $\mu = 3$

φενόδιανύδρα

$$F^{\mu\nu} = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix}$$

$$E_i \equiv F^{0i}$$

$$B_i \equiv \frac{1}{2} \epsilon_{ijk} F^{jk}$$

↑ Levi-Civita

ημέρες αντισυμμετρικός

ευρύσκοτο στις

3 διαστάσεις

$$\epsilon_{123} = \epsilon_{231} = \epsilon_{312} = +1$$

$$\epsilon_{213} = \epsilon_{132} = \epsilon_{321} = -1$$

$$\epsilon_{ijk} = 0 \quad \begin{array}{l} \text{για οποιοδήποτε} \\ \text{αριθμό συνδιασμού} \end{array}$$

$$i, j, k = \{1, 2, 3\}$$

$$\begin{aligned} E_1 &= E_x = F^{0x} & E_2 &= E_y = F^{0y} \\ B_1 &= B_x = \frac{1}{2} \epsilon_{1jk} F^{jk} = \\ &= \frac{1}{2} (\epsilon_{123} F^{23} + \epsilon_{132} F^{32}) \\ &= \frac{1}{2} [\epsilon_{123} F^{23} + (-\epsilon_{123})(-F^{23})] \\ &= F^{23} = B_x \end{aligned}$$

$$T^{\mu'\nu'} = (\bar{T}^{\mu\nu}) = \Lambda^{\mu'}_{\mu} \Lambda^{\nu'}_{\nu} \Lambda^{k'}_{k} T^{\mu\nu k}$$

$$T^{\mu'\nu' k'} = \Lambda^{\mu'}_{\mu} \Lambda^{\nu'}_{\nu} \Lambda^{k'}_{k} T^{\mu\nu k}$$

αντανθούμενος ταγέως 3^{ns}

μείκτος ταγέως 3^{ns}

μετ. E & B σε διαυ (F^m)

$$\begin{matrix} \bar{E} \\ \bar{B} \end{matrix} \xrightarrow{?} \begin{matrix} \bar{E}' \\ \bar{B}' \end{matrix}$$

$$\vec{U} \rightarrow \vec{U}' \rightarrow U^{\mu} \rightarrow U'^{\mu}$$

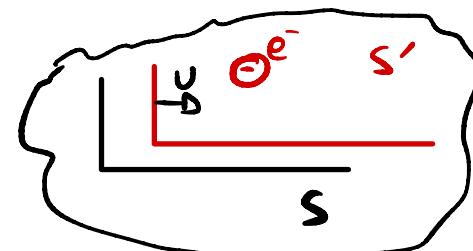
$$(j, j^{\vec{U}}) \quad (j', j'^{\vec{U}})$$

$$F^{\mu\nu} = \begin{bmatrix} 0 & E_x' & E_y' & E_z' \\ -E_x' & 0 & B_z' & -B_y' \\ -E_y' & -B_z' & 0 & B_x' \\ -E_z' & B_y' & -B_x' & 0 \end{bmatrix}$$

$$v = 0 \quad 1 \quad 2 \quad 3$$

$$F^{\mu\nu} = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix} \quad \begin{matrix} 0 = \mu \\ 1 \\ 2 \\ 3 \end{matrix}$$

τυποποιημένος μετ. Lorentz $\vec{U} = U \hat{x}$



$$\Lambda^{\mu'}_{\mu} = \begin{bmatrix} 1 & -ju & 0 & 0 \\ -ju & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\Lambda = [\Lambda^{\mu'}_{\mu}] = [\Lambda^{\nu'}_{\nu}]$$

$$F^{00'} = \Lambda^0_{\mu} \Lambda^{0'}_{\nu} F^{\mu\nu}$$

$$\underline{F^{0'1'} = \Lambda^0_{\mu} \Lambda^{1'}_{\nu} F^{\mu\nu} = E_x'}$$

$$F^{0'1'} = \Lambda^0_0 \Lambda^{1'}_0 F^{00} + \Lambda^0_0 \Lambda^{1'}_1 F^{01} + \Lambda^0_0 \Lambda^{1'}_2 F^{02} + \Lambda^0_0 \Lambda^{1'}_3 F^{03}$$

$$\Lambda^0_1 \Lambda^{1'}_0 F^{10} + \Lambda^0_1 \Lambda^{1'}_1 F^{11} + \Lambda^0_1 \Lambda^{1'}_2 F^{12} + \Lambda^0_1 \Lambda^{1'}_3 F^{13}$$

$$\Lambda^0_2 \Lambda^{1'}_0 F^{20} + \Lambda^0_2 \Lambda^{1'}_1 F^{21} + \Lambda^0_2 \Lambda^{1'}_2 F^{22} + \Lambda^0_2 \Lambda^{1'}_3 F^{23}$$

$$\Lambda^0_3 \Lambda^{1'}_0 F^{30} + \Lambda^0_3 \Lambda^{1'}_1 F^{31} + \Lambda^0_3 \Lambda^{1'}_2 F^{32} + \Lambda^0_3 \Lambda^{1'}_3 F^{33}$$

$$F^{0'} = \Lambda^0_0 \Lambda^1_0 F^{00} + \Lambda^0_0 \Lambda^1_1 F^{01} + \Lambda^0_0 \Lambda^1_2 F^{02} + \Lambda^0_0 \Lambda^1_3 F^{03}$$

$$\cancel{\Lambda^0_1 \Lambda^1_0 F^{10}} + \cancel{\Lambda^0_1 \Lambda^1_1 F^{11}} + \cancel{\Lambda^0_1 \Lambda^1_2 F^{12}} + \cancel{\Lambda^0_1 \Lambda^1_3 F^{13}}$$

$$\cancel{\Lambda^0_2 \Lambda^1_0 F^{20}} + \cancel{\Lambda^0_2 \Lambda^1_1 F^{21}} + \cancel{\Lambda^0_2 \Lambda^1_2 F^{22}} + \cancel{\Lambda^0_2 \Lambda^1_3 F^{23}}$$

$$\cancel{\Lambda^0_3 \Lambda^1_0 F^{30}} + \cancel{\Lambda^0_3 \Lambda^1_1 F^{31}} + \cancel{\Lambda^0_3 \Lambda^1_2 F^{32}} + \cancel{\Lambda^0_3 \Lambda^1_3 F^{33}}$$

$$\begin{bmatrix} 0 & -\gamma u & 0 & 0 \\ -\gamma u & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$v = \begin{matrix} 0 & 1 & 2 & 3 \end{matrix} \quad \boxed{\mu = \begin{matrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{matrix}} \quad \begin{matrix} = \gamma^2 E_x - (\gamma u)^2 E_x \\ = E_x \\ \gamma^2 (1-u^2) = 1 \end{matrix}$$

 $\Lambda^{\mu'}_{\mu}$ $F^{\mu\nu}$

$$F^{\mu'\nu'} = \Lambda^{\mu'}_{\mu} \Lambda^{\nu'}_{\nu} \boxed{F^{\mu\nu}} \quad \rightarrow \quad F' = \Lambda \quad F \quad \Lambda^T$$

"Gesetzwege", "Prinzipien"

$$\boxed{F^{\mu'\nu'}} = \boxed{\Lambda^{\mu'}_{\mu}} \boxed{F^{\mu\nu}} \boxed{\Lambda^{\nu'}_{\nu}}^T$$

$$C_{ij} = \sum_k A_{ik} B_{kj}$$

$$\rightarrow [C] = [A] \cdot [B]$$

$$D_{ij} = \sum_k B_{jk} A_{ik}$$

$$\rightarrow [D] = [A] [B]^T$$

$$F' = \Lambda \quad F \quad \Lambda'$$

$$\boxed{F^{\mu'\nu'}} = \boxed{\Lambda^{\mu'}_{\mu}} \quad \boxed{F^{\mu\nu}} \quad \boxed{\Lambda^{\nu'}_{\nu}}^T$$

$$\begin{bmatrix} 0 & -\gamma u & 0 & 0 \\ -\gamma u & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & -\gamma u & 0 & 0 \\ -\gamma u & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} \gamma u E_x & \gamma E_x & \gamma E_y - \gamma u B_z & \gamma E_z + \gamma u B_y \\ -\gamma E_y & -\gamma u E_x & -\gamma u E_y + \gamma B_z & -\gamma u E_z - \gamma B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & -\gamma u & 0 & 0 \\ -\gamma u & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} \gamma u E_x & \gamma E_x & \gamma E_y - \gamma u B_z & \gamma E_z + \gamma u B_y \\ -\gamma E_y & -\gamma u E_x & -\gamma u E_y + \gamma B_z & -\gamma u E_z - \gamma B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & -\gamma u & 0 & 0 \\ -\gamma u & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{array}{cccc} \gamma^2 u E_x - \gamma^2 u E_x & -\gamma^2 u^2 E_x + \gamma^2 E_x & \gamma E_y - \gamma u B_z & \gamma E_z + \gamma u B_y \\ -\gamma^2 E_x + \gamma^2 u^2 E_x & \gamma^2 u E_x - \gamma^2 u E_x & -\gamma u E_y + \gamma B_z & -\gamma u E_z - \gamma B_y \\ -\gamma E_y + \gamma u B_z & \gamma u E_y - \gamma B_z & 0 & B_x \\ -\gamma E_z - \gamma u B_y & +\gamma u E_z + \gamma B_y & -B_x & 0 \end{array}$$

$$\gamma^2(1-u^2) = 1$$

$$\begin{bmatrix} 0 & E_x & \gamma(E_y - u B_z) & \gamma(E_z + u B_y) \\ -E_x & 0 & \gamma(B_z - u E_y) & -\gamma(B_y + u E_z) \\ -\gamma(E_y - u B_z) & -\gamma(B_z - u E_y) & 0 & B_x \\ -\gamma(E_z + u B_y) & \gamma(B_y + u E_z) & -B_x & 0 \end{bmatrix}$$

$$F^{\mu\nu} = \begin{bmatrix} 0 & E'_x & E'_y & E'_z \\ -E'_x & 0 & B'_z - B'_y & \\ -E'_y - B'_z & 0 & B'_x & \\ -E'_z & B'_y - B'_x & 0 & \end{bmatrix} \quad \begin{array}{l} E'_x = E_x \\ E'_y = \gamma(E_y - u B_z) \\ E'_z = \gamma(E_z + u B_y) \end{array} \quad \left. \begin{array}{l} E'_{||} = E_{||} \\ \bar{E}'_{\perp} = \gamma(\bar{E}_{\perp} + \bar{U} \times \bar{B}) \\ = \gamma(\bar{E}_{\perp} + \bar{U} \times \bar{B}_{\perp}) \end{array} \right\}$$

$$\bar{U} = u \hat{x} \quad \bar{U} \times \bar{B} = \begin{vmatrix} i & j & k \\ u & 0 & 0 \\ B_x & B_y & B_z \end{vmatrix} = 0\hat{i} + (-u B_z)\hat{j} + (u B_y)\hat{k}$$

$$(\bar{U} \times \bar{B})_i = \sum_j \sum_k \epsilon_{ijk} u_j B_k$$

$$\vec{E}'_{||} = \vec{E}_{||}$$

$$\begin{aligned} \bar{E}'_{||} &= \gamma(\bar{E}_{\perp} + \bar{U} \times \bar{B}) \\ &= \gamma(\bar{E}_{\perp} + \bar{U} \times \bar{B}_{\perp}) \end{aligned}$$

$$\bar{B}'_{||} = \bar{B}_{||}$$

$$\begin{aligned} \bar{B}'_{\perp} &= \gamma(\bar{B}_{\perp} - \bar{U} \times \bar{E}) \\ \bar{B}'_{\perp} &= \gamma(\bar{B}_{\perp} - \bar{U} \times \bar{E}_{\perp}) \end{aligned}$$

ΔΙΛΚΟΣ ΤΑΝΥΓΤΗΣ

$$\tilde{F}^{\mu\nu} = \frac{1}{2} \epsilon^{\mu\nu\kappa\lambda} F_{\kappa\lambda}$$

↑
4-diagto symbole Levi-Civita

$$F_{\mu\nu} = n_{\mu k} n_{\nu l} F^{kl}$$

$$[F^{\mu\nu}] = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z - B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y - B_x & 0 \end{bmatrix} = \begin{bmatrix} 0 & E^T \\ -E & B \end{bmatrix} = F$$

$$[n_{\mu\nu}] = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & I \end{bmatrix} = n$$

$$[F_{\mu\nu}] = n F n^T = \begin{bmatrix} -1 & 0 \\ 0 & I \end{bmatrix} \begin{bmatrix} 0 & E^T \\ -E & B \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & I \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 0 \\ 0 & I \end{bmatrix} \begin{bmatrix} 0 & E^T \\ +E & B \end{bmatrix} = \begin{bmatrix} 0 & -E^T \\ E & B \end{bmatrix}$$

$$F_{\mu\nu} = \begin{bmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & B_z & -B_y \\ E_y & -B_z & 0 & B_x \\ E_z & B_y & -B_x & 0 \end{bmatrix}$$

$$\epsilon^{\mu\nu\kappa\lambda} = (-1)^P \epsilon^{0123}$$

$$\epsilon^{0123} = +1 \quad \epsilon_{0123} = -1$$

P = οροτιμη μετανεγμων

4⁴ στοιχεια

αν δυο σειρες είναι ίδιοι

$$\text{π.χ. } \epsilon^{0012} = -\epsilon^{0012} = 0$$

τοτε το στοχειο του

τανυγτη είναι μηδεν

$$\epsilon_{\mu\nu\kappa\lambda} \epsilon^{\mu\nu\kappa\lambda} = -24 \text{ ακρων}$$

$$\begin{matrix} 0 & 1 & 2 & 3 \\ 1 & 2 & 3 & 0 \\ 2 & 3 & 0 & 1 \end{matrix}$$

$$\tilde{F}^{\mu\nu} = \begin{bmatrix} 0 & B_x & B_y & B_z \\ -B_x & 0 & -E_z & E_y \\ -B_y & E_z & 0 & -E_x \\ -B_z & -E_y & E_x & 0 \end{bmatrix}$$

$$\tilde{F}^{00} = \frac{1}{2} \epsilon^{00\kappa\lambda} F_{\kappa\lambda} = 0$$

$$\tilde{F}^{01} = \frac{1}{2} \epsilon^{01\kappa\lambda} F_{\kappa\lambda} = \frac{1}{2} \left(\epsilon^{0123} F_{23} + \epsilon^{0132} F_{32} \right)$$

$$\frac{1}{2} \left(\epsilon^{0123} F_{23} + (-\epsilon^{0123}) (-F_{23}) \right) = F_{23} = B_x$$

$$\tilde{F}^{02} = \frac{1}{2} \epsilon^{02\kappa\lambda} F_{\kappa\lambda} = \frac{1}{2} \left(\epsilon^{0213} F_{13} + \epsilon^{0231} F_{31} \right) = F_{31} = B_y$$

$$\tilde{F}^{03} = \frac{1}{2} \epsilon^{03\kappa\lambda} F_{\kappa\lambda} = \frac{1}{2} \left(\epsilon^{0312} F_{12} + \epsilon^{0321} F_{21} \right) = F_{12} = B_z$$

$$0312 \perp 0132 \perp 0123$$

εξεταζω τον μεταβοληγο της $\bar{\nabla} \cdot \bar{B} = 0 \rightarrow \bar{\nabla}' \cdot \bar{B}' = ?$

$$\partial_x = \frac{\partial}{\partial x} \quad \text{J'a} \quad \vec{U} = U \hat{x}$$

$$\bar{\nabla} = (\partial_x, \partial_y, \partial_z) \quad \rightarrow \quad \bar{\nabla}' = \left(\frac{\partial}{\partial x'}, \frac{\partial}{\partial y'}, \frac{\partial}{\partial z'} \right)$$

$$\bar{B} \rightarrow \bar{B}' \quad \rightarrow \bar{\nabla}' = \left(J \frac{\partial}{\partial x'} + Ju \frac{\partial}{\partial t}, \frac{\partial}{\partial y'}, \frac{\partial}{\partial z'} \right)$$

$$\frac{\partial}{\partial x'} = J \frac{\partial}{\partial x} \frac{\partial x}{\partial x'} + \frac{\partial}{\partial t} \frac{\partial t}{\partial x'} = J \frac{\partial}{\partial x} + Ju \frac{\partial}{\partial t}$$

$$x = x(x', t') = J(x' + ut')$$

$$t = t(x', t') = J(t' + ux')$$

$$y' = y$$

$$z' = z$$

$$\frac{\partial}{\partial y'} = \frac{\partial}{\partial y}$$

$$\frac{\partial}{\partial z'} = \frac{\partial}{\partial z}$$

$$\bar{B}'_{||} = \bar{B}_{||} = B_x \hat{x}$$

$$\bar{B}'_{\perp} = J(\bar{B}_{\perp} - \bar{U} \times \bar{E}) = J(B_y \hat{y} + B_z \hat{z} - u \hat{x} \times (E_x \hat{x} + E_y \hat{y} + E_z \hat{z}))$$

$$\bar{B}' = (B_x, J(B_y + u E_z), J(B_z - u E_y))$$

$$\bar{\nabla}' \bar{B}' = \left(J \frac{\partial}{\partial x} + Ju \frac{\partial}{\partial t}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) (B_x, J(B_y + u E_z), J(B_z - u E_y))$$

$$= J \frac{\partial B_x}{\partial x} + Ju \frac{\partial B_x}{\partial t} + J \frac{\partial B_y}{\partial y} + Ju \frac{\partial B_z}{\partial y} + J \frac{\partial B_z}{\partial z} - Ju \frac{\partial E_y}{\partial z}$$

$$= J \frac{\partial B_x}{\partial x} + J \frac{\partial B_y}{\partial y} + J \frac{\partial B_z}{\partial z} + Ju \frac{\partial E_z}{\partial y} + Ju \frac{\partial B_x}{\partial t} - Ju \frac{\partial E_y}{\partial z}$$

$$= J(\bar{\nabla} \bar{B}) + Ju \left(\frac{\partial B_x}{\partial t} + (B_y E_z - B_z E_y) \right)$$

$$\frac{\partial \bar{B}}{\partial t} \Big|_x \quad (\bar{\nabla} \times \bar{E})_x$$

$$= J(\bar{\nabla} \bar{B}) + Ju \left[\frac{\partial \bar{B}}{\partial t} + (\bar{\nabla} \times \bar{E}) \right]_x = 0$$

$$\bar{\nabla} \bar{B} = 0$$

$$\bar{\nabla} \times \bar{E} + \frac{\partial \bar{B}}{\partial t} = 0$$

$$\left. \begin{array}{l} \bar{\nabla} \cdot \bar{E} = 0 \\ \bar{\nabla} \cdot \bar{B} = 0 \\ \bar{\nabla} \times \bar{E} + \frac{\partial \bar{B}}{\partial t} = 0 \\ \bar{\nabla} \times \bar{B} - \mu_0 \epsilon_0 \frac{\partial \bar{E}}{\partial t} = 0 \end{array} \right\} \quad \rho = 0 \quad \bar{\Delta} = \bar{0} \quad (\mu_0 \epsilon_0)^{-1/2} = C = 1$$

ε₀ & μ₀ Maxwell's law to Maxwell's law

$$\partial_\mu F^{\mu\nu} = 0 \rightarrow \bar{\nabla} \bar{E} = 0 \mid \frac{\partial \bar{E}}{\partial t} - \bar{\nabla} \times \bar{B} = 0$$

$$\partial_\mu \tilde{F}^{\mu\nu} = 0 \rightarrow \bar{\nabla} \bar{B} = 0 \mid \frac{\partial \bar{B}}{\partial t} + \bar{\nabla} \times \bar{E} = 0$$

v=0

$$\begin{aligned} \partial_\mu F^{\mu 0} &= 0 \\ \partial_t F^{00} + \partial_x F^{10} + \partial_y F^{20} + \partial_z F^{30} &= 0 \\ 0 + \partial_x E_x + \partial_y E_y + \partial_z E_z &= 0 \\ \bar{\nabla} \cdot \bar{E} &= 0 \end{aligned}$$

v=1

$$\begin{aligned} \partial_\mu F^{\mu 1} &= \partial_t F^{01} + \partial_x F^{11} + \partial_y F^{21} + \partial_z F^{31} \\ &= \partial_t E_x + 0 + \partial_y (-B_z) + \partial_z B_y \\ &= \left[\frac{\partial}{\partial t} \bar{E} - (\bar{\nabla} \times \bar{B}) \right]_x \end{aligned}$$

$$\begin{matrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{matrix} =$$

v=1

v=1

αναλογία του H/M νεδιού

- $\frac{1}{2} F^{\mu\nu} F_{\mu\nu} = \frac{1}{2} (-\vec{E} \cdot \vec{E} + \vec{B} \cdot \vec{B} - \vec{E} \cdot \vec{E} + \vec{B} \cdot \vec{B}) = -E^2 + B^2 \equiv I_1$
- $\frac{1}{4} F^{\mu\nu} F_{\mu\nu} = \frac{1}{4} (-\vec{E} \cdot \vec{B} - \vec{E} \cdot \vec{B} - \vec{E} \cdot \vec{B} - \vec{E} \cdot \vec{E}) = -\vec{E} \cdot \vec{B} \equiv I_2$
- $\frac{1}{2} F_{\nu}^{\mu} F^{\nu}_{\mu} = \frac{1}{2} n_{\nu k} F^{\mu k} F^{\nu}_{\mu} = \frac{1}{2} F^{\mu k} n_{\nu k} F^{\nu}_{\mu} = \frac{1}{2} F^{\mu k} F_{k\mu} = \frac{1}{2} F^{\mu\nu} F_{\nu\mu}$
- $n_{\mu k} F^{\mu k} = F^{\mu}_{\mu} = \text{tr}([F^{\mu\nu}]) = 0 + 0 + 0 + 0 = \frac{1}{2} F^{\mu\nu} (-F_{\mu\nu}) = -I_1$

- $F^{\alpha\beta} F_{\beta\gamma} F^{\gamma\delta} F_{\delta\alpha} = g(I_1, I_2)$

- $F^{\alpha\beta} F_{\beta\gamma} F^{\gamma\delta} F_{\delta\alpha} = f(I_1, I_2)$

F

$$n = \begin{bmatrix} -1 & 0 \\ 0 & I \end{bmatrix}$$

$$[F^{\mu\nu}] = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix}$$

$$[F_{\mu\nu}] = \begin{bmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & B_z & -B_y \\ E_y & -B_z & 0 & B_x \\ E_z & B_y & -B_x & 0 \end{bmatrix}$$

$$[\tilde{F}^{\mu\nu}] = \begin{bmatrix} 0 & B_x & B_y & B_z \\ -B_x & 0 & -E_z & E_y \\ -B_y & E_z & 0 & -E_x \\ -B_z & -E_y & E_x & 0 \end{bmatrix}$$

Τα ευαρτησιακάς ανεξαρτήτικά αναλογίατα είναι το πολύ δύο
(Θεωρητικά GS.1 επιμειωσεις χρηστοδουλακης κορφιατην)

ΠΕΡΙΠΤΩΣΗ $v \in$

$\vec{E} \cdot \vec{B} \neq 0$

Εστω $\frac{\sigma_{TL}}{v} = v \hat{z}$ $\vec{E} \times \vec{B} / EB \sin \phi = \hat{z}$

$\vec{E}_{||}' = \vec{E}_{||} = 0$

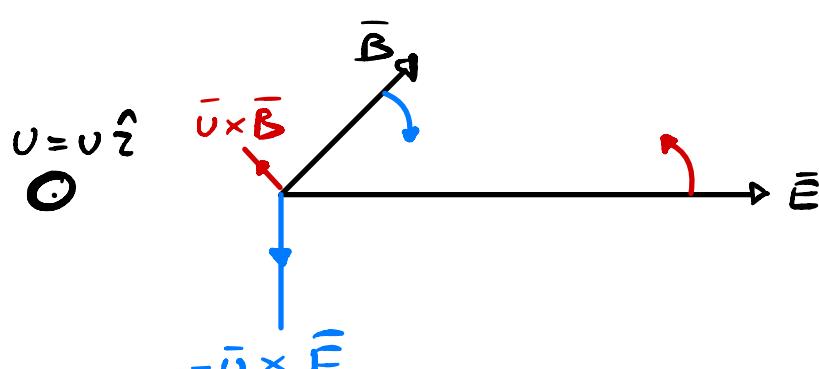
$\vec{B}_{||}' = \vec{B}_{||} = 0$

$\vec{E} = \vec{E}_T$

$\vec{B} = \vec{B}_T$

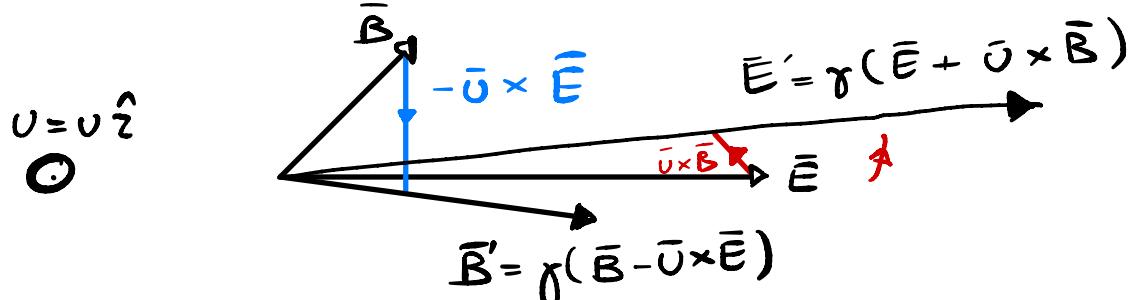
π.χ. $-B^2 + E^2 > 0$

$\vec{B}' \quad \vec{E}'$



$\vec{B}' = \gamma (\vec{B} - \bar{u} \times \vec{E})$

$\vec{E}' = \gamma (\vec{E} + \bar{u} \times \vec{B})$



$$F_p^v = n_r F^{vv}$$

$$[F_p^v] = n \cdot F$$

$$= \begin{bmatrix} -1 & 0 \\ 0 & I \end{bmatrix} \cdot \begin{bmatrix} O & E^T \\ -E & B \end{bmatrix} = \begin{bmatrix} O & -E^T \\ -E & B \end{bmatrix} =$$

$$\begin{bmatrix} O & -E_x & -E_y & -E_z \\ -E_x & O & B_z & -B_y \\ -E_y & -B_z & O & B_x \\ -E_z & B_y & -B_x & O \end{bmatrix}$$

$n \cdot F$

$F \cdot n$

$AB \neq BA$

$AB - BA = 0$

$$F_p^v = \text{tr} \left(\begin{bmatrix} O & -E_x & -E_y & -E_z \\ -E_x & O & B_z & -B_y \\ -E_y & -B_z & O & B_x \\ -E_z & B_y & -B_x & O \end{bmatrix} \right) = O + O + O + O$$

ΔΕΡΙΛΤΩΓΗ ΜΕ
 $\bar{E} \cdot \bar{B} = 0$

$$E^2 \neq B^2$$

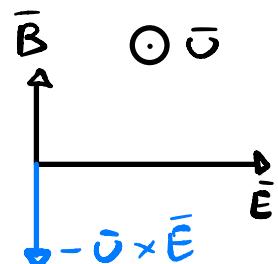
$$E^2 > B^2$$

$$E^2 < B^2$$

υηαρχει S'

στο ονοιο

$$\bar{B}' = 0$$

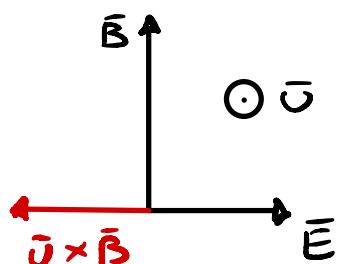


$$\bar{B}' = \gamma(\bar{B} - \bar{u} \times \bar{E}) \\ = 0$$

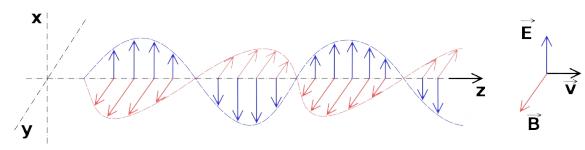
υηαρχει S'

στο ονοιο

$$\bar{E}' = 0$$



$$\bar{E}' = \gamma(\bar{E} + \bar{u} \times \bar{B}) \\ = 0$$



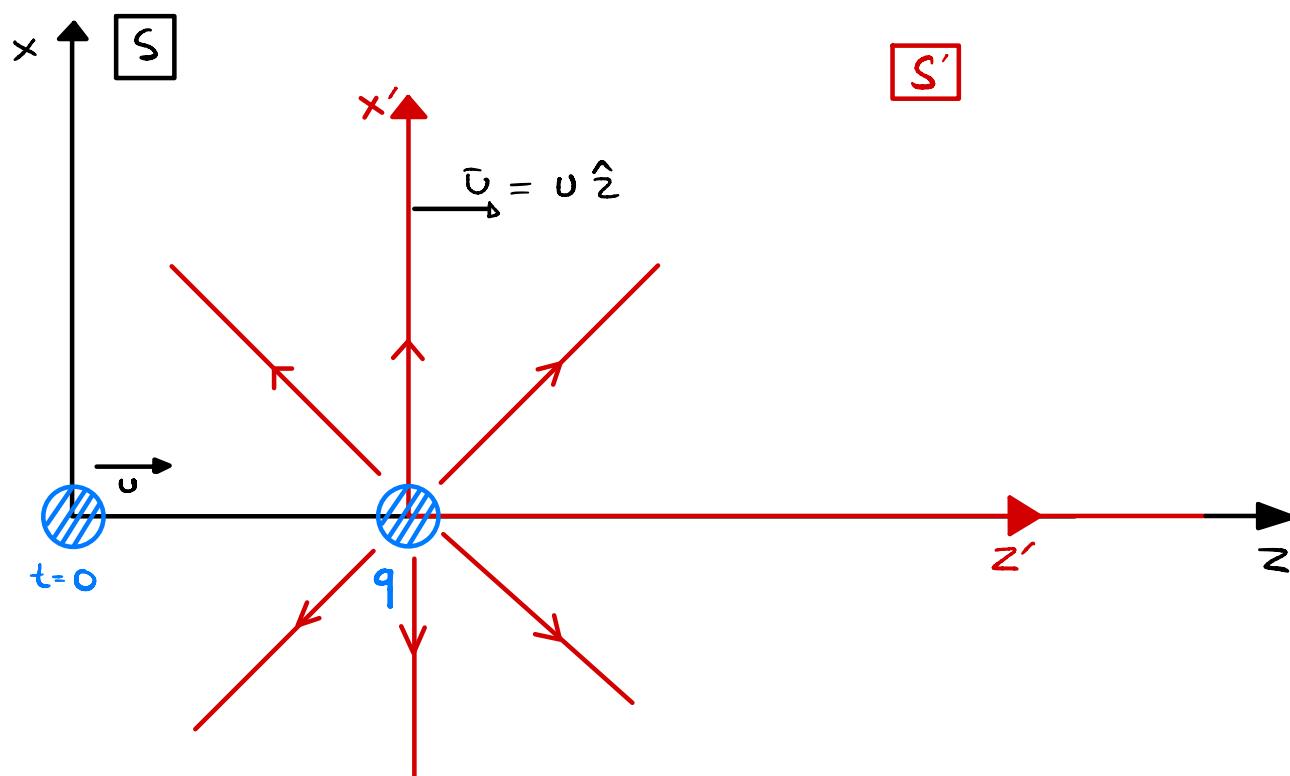
$$E^2 = B^2$$

ΗΜ τυπωτα

σταδ. ενισχυση πολωνης

$$\begin{aligned} \bar{B}' &= \gamma(\bar{B} - \bar{u} \times \bar{E}) \\ \bar{B} &\uparrow \\ \bar{B} &\rightarrow \\ -\bar{u} \times \bar{E} &\leftarrow \\ \bar{u} \times \bar{B} &\rightarrow \\ \bar{E}' &= \gamma(\bar{E} + \bar{u} \times \bar{B}) \end{aligned}$$

$$\begin{aligned} \bar{B}' &\uparrow \\ \bar{B} &\uparrow \\ \bar{B} &\rightarrow \\ \bar{u} \times \bar{B} &\leftarrow \\ -\bar{u} \times \bar{E} &\rightarrow \\ \bar{E}' &= \gamma(\bar{E} + \bar{u} \times \bar{B}) \end{aligned}$$

S'

$$\vec{E}' = \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{(r')^2}$$

$$\frac{\hat{r}}{r^2} = -\frac{\vec{r}'}{r'^3} = \frac{(x', y', z')}{((x')^2 + (y')^2 + (z')^2)^{3/2}}$$

$$\begin{aligned}\bar{E}_{||} &= \bar{E}'_{||} \\ \bar{E}_{\perp} &= \gamma (\bar{E}'_{\perp} - \bar{v} \times \bar{B}')\end{aligned}$$

$$\begin{aligned}\bar{B}_{||} &= \bar{B}'_{||} \\ \bar{B}_{\perp} &= \gamma (\cancel{\bar{B}_{\perp}} + \bar{v} \times \bar{E})\end{aligned}$$

S

$$E_x = \gamma (E'_x - \bar{v} \times \cancel{B}'_T)$$

$$= \gamma \frac{A x'}{((x')^2 + (y')^2 + (z')^2)^{3/2}}$$

$$A \equiv \frac{q}{4\pi\epsilon_0}$$

$$E_y = \gamma (E'_y - \bar{v} \times \cancel{B}'_T)$$

$$= \gamma \frac{A y'}{((x')^2 + (y')^2 + (z')^2)^{3/2}}$$

$$E_z = E'_z$$

$$= A \frac{z'}{((x')^2 + (y')^2 + (z')^2)^{3/2}}$$

$$z' = \gamma(z - vt)$$

$$x' = x$$

$$y' = y$$

$$E_x \Big|_{t=0} = \gamma \frac{A_x}{((x)^2 + (y)^2 + (\gamma z)^2)^{3/2}}$$

$$E_y \Big|_{t=0} = \gamma \frac{A_y}{((x)^2 + (y)^2 + (\gamma z)^2)^{3/2}}$$

$$E_z \Big|_{t=0} = \gamma \frac{A_z}{((x)^2 + (y)^2 + (\gamma z)^2)^{3/2}}$$

$$\vec{E} = \gamma \frac{A}{((x)^2 + (y)^2 + (\gamma z)^2)^{3/2}} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

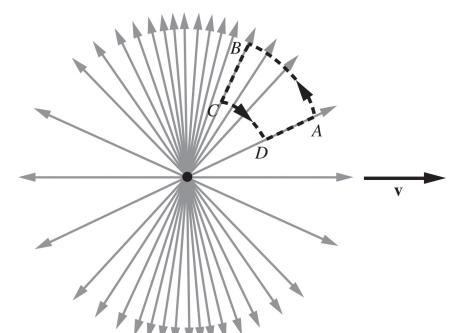
$$\vec{E} = \frac{1}{\gamma^2(1 - v^2 \sin^2 \theta)^{3/2}} \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2}$$

$$((x)^2 + (y)^2 + (\gamma z)^2)^{3/2} = [r^2 \sin^2 \theta + \gamma^2 r^2 \cos^2 \theta]^{3/2} = r^3 (\sin^2 \theta + \gamma^2 (1 - \sin^2 \theta))^{3/2} = r^3 (\gamma^2 - \gamma^2 v^2 \sin^2 \theta)^{3/2} = r^3 \gamma^3 (1 - v^2 \sin^2 \theta)^{3/2}$$

$$\Theta = 0 \quad \vec{E} = \frac{1}{\gamma^2} A \frac{\hat{r}}{r^2}$$

$$\Theta = \frac{\pi}{2} \quad \vec{E} = A \frac{\hat{r}}{r^2}$$

|



$$\bar{B}' = 0 \quad \bar{B}_{||}' = 0 = \bar{B}_{||}$$

$$\bar{B}_{\perp}' = 0 = \gamma (\bar{B}_{\perp} - \bar{v} \times \bar{E}) = 0$$

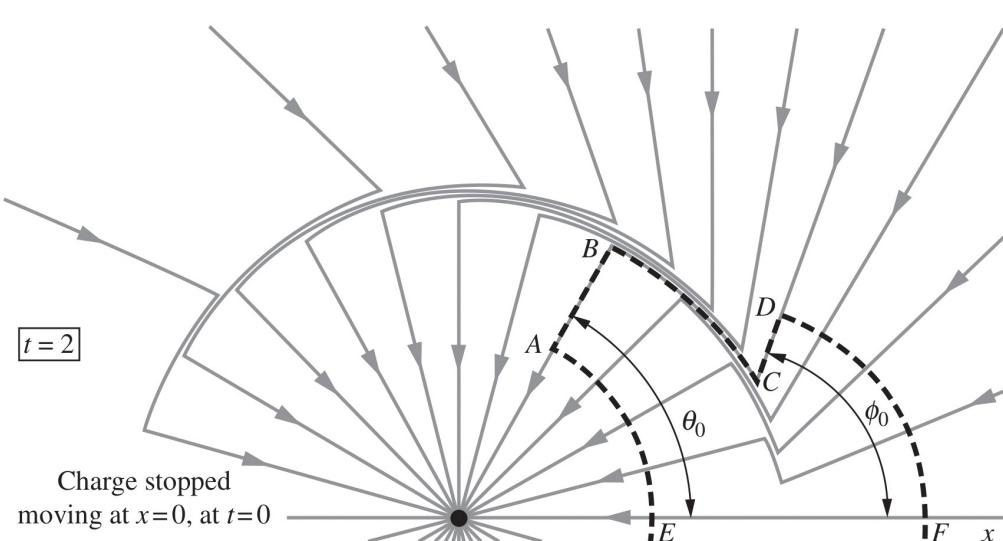
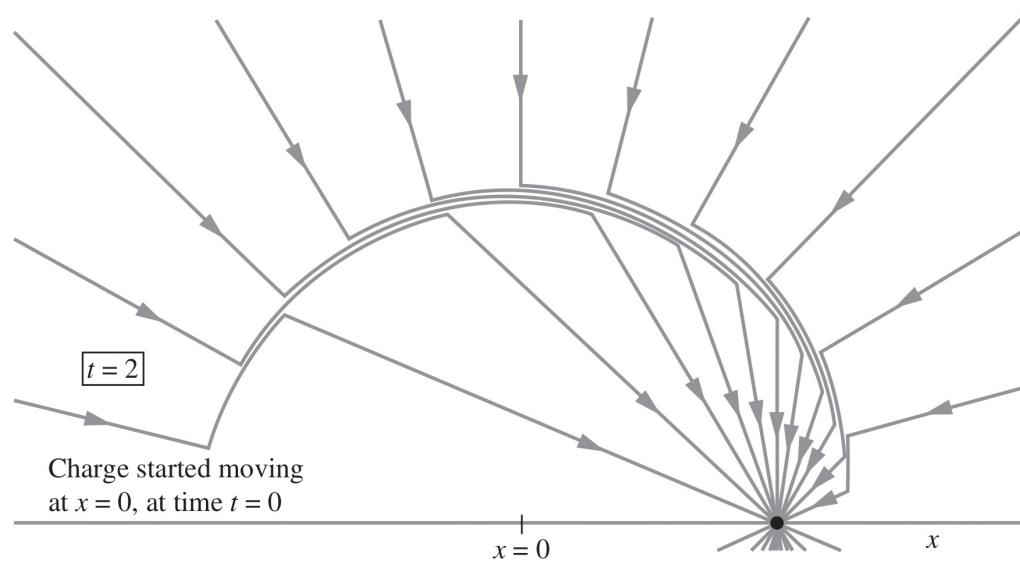
$$\bar{B} = \bar{v} \times \bar{E} \quad \text{or} \quad \bar{B}' = 0$$

$$v \cdot E \cdot (\hat{z} \times \hat{r})$$

$$\hookrightarrow \sin \theta \hat{\phi}$$

$$\bar{B} = \frac{v \sin \theta}{\gamma^2 (1 - v^2 \sin^2 \theta)^{3/2}} \frac{q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2} \hat{\phi}$$

Electricity & Magnetism
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$$\frac{d\vec{P}^\mu}{dt} = \frac{d}{dt} \left[\begin{matrix} E \\ \vec{P} \end{matrix} \right] = \left[\begin{matrix} \gamma \frac{dE/dt} \\ \gamma \frac{d\vec{P}/dt} \end{matrix} \right] = q \vec{F}^{\mu\nu} \cdot \vec{U}_\nu = q \left[\begin{matrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{matrix} \right] \left[\begin{matrix} -\gamma \\ \gamma U_x \\ \gamma U_y \\ \gamma U_z \end{matrix} \right]$$

$$U_\nu = \eta_{\mu\nu} U^\mu$$

$$\left[\begin{matrix} -1 & 0 \\ 0 & I \end{matrix} \right] \left[\begin{matrix} \gamma \\ \vec{U} \end{matrix} \right]$$

$$= \left[\begin{matrix} \gamma(E_x U_x + E_y U_y + E_z U_z) \\ \gamma(E_x + B_z U_y - B_y U_z) \\ \gamma(E_y - B_z U_x + B_x U_z) \\ \gamma(E_z + B_y U_x - B_x U_y) \end{matrix} \right] = \left[\begin{matrix} \gamma(q \vec{E} \cdot \vec{U}) \\ \gamma q(\vec{E} + \vec{\omega} \times \vec{B}) \end{matrix} \right] = \left[\begin{matrix} \gamma(\vec{F}_L \cdot \vec{U}) \\ \gamma \vec{F}_L \end{matrix} \right]$$

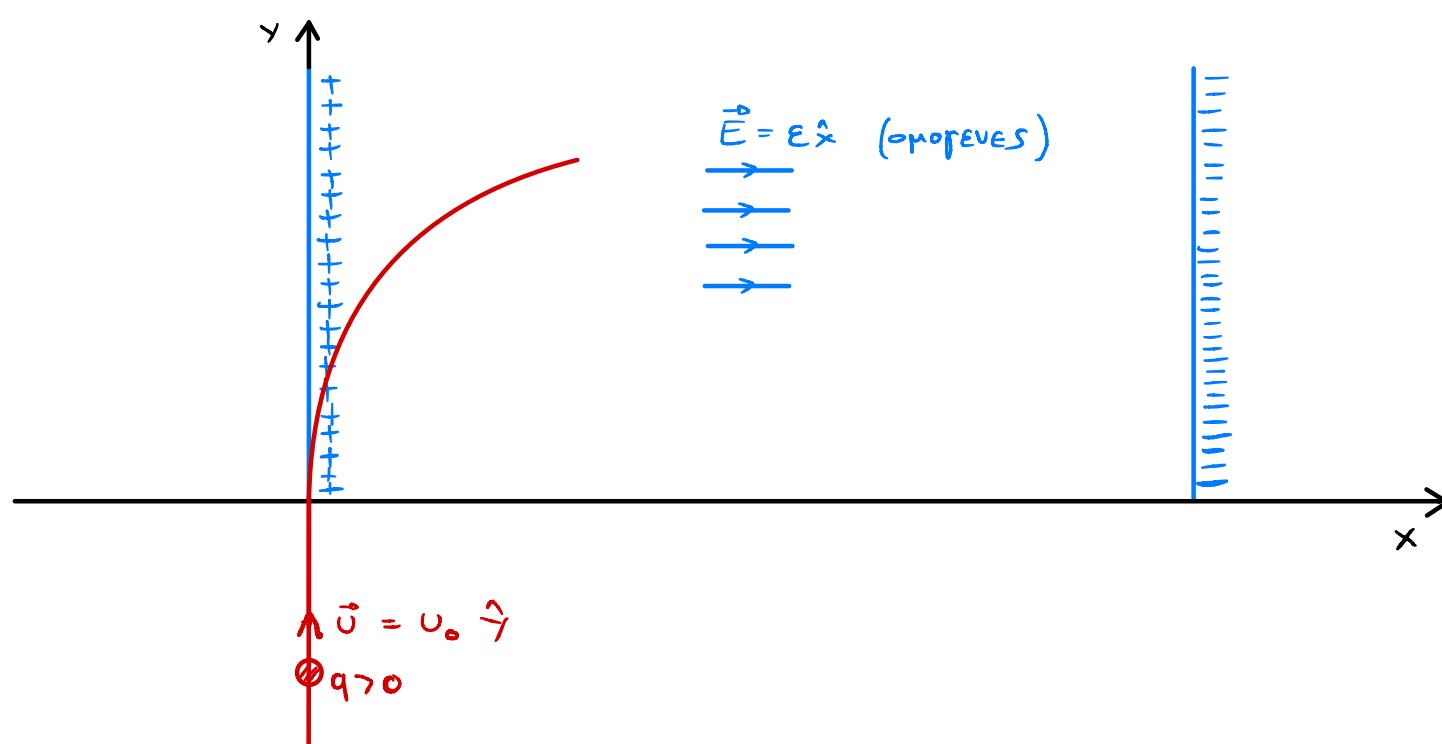
$$(\vec{U} \times \vec{B})_i = \epsilon_{ijk} U_j B_k$$

$$\begin{aligned} (\vec{U} \times \vec{B})_x &= U_y B_z - U_z B_y \\ (\vec{U} \times \vec{B})_y &= B_x U_z - B_z U_x \\ (\vec{U} \times \vec{B})_z &= B_y U_x - B_x U_y \end{aligned}$$

$$\begin{aligned} \vec{U} \cdot \vec{F}_L &= \vec{U} q (\vec{E} + \vec{\omega} \times \vec{B}) \\ &= q \vec{E} \cdot \vec{U} \end{aligned}$$

$$\frac{d\vec{P}}{dt} = \frac{d(\vec{P}^\mu \vec{U})}{dt} = \vec{F}_L = q(\vec{E} + \vec{\omega} \times \vec{B})$$

κινητή φορτίου σε επαθέρο Ε-μεδία



$$\vec{F}_\perp = q(\vec{E} + \vec{U} \times \vec{B}) - q\epsilon \hat{x} = \frac{d\vec{P}}{dt} = \frac{d}{dt}(mv\hat{x})$$

$$x(t), y(t) = ? \\ u_x(t), u_y(t) = ?$$

A: $u_y(t) = 6\pi a \vartheta$

46%

B: $u_y(t) = \alpha u_0 u_0 \theta$

15%

C: $u_y(t) = \phi \vartheta u_0 u_0 \theta$

39%

$$\frac{d\vec{P}^k}{dt} = q \begin{bmatrix} \frac{dE}{dt} \\ \frac{dP_x}{dt} \\ \frac{dP_y}{dt} \\ \frac{dP_z}{dt} \end{bmatrix} = q \begin{bmatrix} 0 & \epsilon & 0 & 0 \\ -\epsilon & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \vec{v} \begin{bmatrix} -1 \\ u_x \\ u_y \\ u_z \end{bmatrix}$$

$$\frac{dE}{dt} = q\epsilon u_x = (q\epsilon \hat{x}) \cdot (u_x \hat{x}) = \vec{F} \cdot \vec{U}$$

$$\dot{P}_x = q\epsilon \quad \Rightarrow \quad P_x = q\epsilon t + \cancel{6\pi a \theta}$$

$$\dot{P}_y = 0 \quad \Rightarrow \quad P_y = 6\pi a \theta = \frac{m u_0}{\sqrt{1 - u_0^2}} = \frac{m u_y(t)}{\sqrt{1 - u^2}} = P_{y0}$$

$$\dot{P}_z = 0 \quad \Rightarrow \quad P_z = 6\pi a \vartheta = 0$$

$$u_x(t) = \frac{dx}{dt} = \frac{P_x}{E} = \frac{q\epsilon t}{\sqrt{m^2 + P_{y0}^2 + P_x^2}} = \frac{q\epsilon t}{\underbrace{\sqrt{m^2 + P_{y0}^2 + (q\epsilon t)^2}}_{\sqrt{E_0^2 + (q\epsilon t)^2}}} = \frac{q\epsilon t}{\sqrt{E_0^2 + (q\epsilon t)^2}}$$

$$= \frac{q\epsilon t / E_0}{\sqrt{1 + (\frac{q\epsilon}{E_0} t)^2}}$$

$$E_0^2 = m^2 + P_{y0}^2$$

$$A \equiv \frac{q\epsilon}{E_0}$$

$$dx = \frac{1}{A} \int \frac{At}{\sqrt{1 + (At)^2}} d(At)$$

$$x(t) = \frac{1}{A} \sqrt{1 + (At)^2} + e^{\tau a} \theta \quad | \quad x(0) = 0 \Rightarrow e^{\tau a} \theta = -\frac{1}{A}$$

$$x(t) = \frac{1}{A} (\sqrt{1 + (At)^2} - 1)$$

exoupe $P_y(t) = P_{y0} = e^{\tau a} \theta$

$$\begin{aligned} \frac{dy}{dt} &= \frac{P_y(t)}{E} = \frac{P_{y0}}{\sqrt{m^2 + P_{y0}^2 + P_x^2}} \\ &= \frac{P_{y0}}{\sqrt{E_0^2 + (q\varepsilon t)^2}} = \frac{P_{y0}/E_0}{\sqrt{1 + (At)^2}} = u_y(t) \end{aligned}$$

$$dy = \int \frac{P_{y0}/E_0}{\sqrt{1 + (At)^2}} dt$$

$$\sinh \omega = At$$

$$\cosh^2 \omega = 1 + \sinh^2 \omega$$

$$\frac{d\omega}{A} \cosh \omega = dt$$

$$\begin{aligned} \int dy &= P_{y0}/E_0 \int \frac{\cosh \omega}{\sqrt{1 + \sinh^2 \omega}} \frac{d\omega}{A} \\ &= \frac{P_{y0}}{AE_0} \int d\omega = \frac{P_{y0}}{AE_0} \omega + e^{\tau a} \theta \quad y(0) = 0 \\ y(t) &= \frac{P_{y0}}{AE_0} \sinh^{-1}(At) \end{aligned}$$

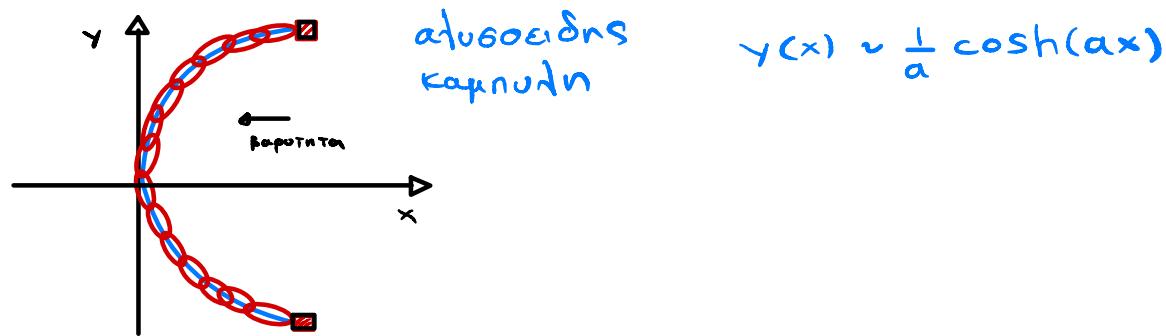
arcsinh
arsinh
\sinh^{-1}

$$x(t) = \frac{E_0}{q\varepsilon} \left(\sqrt{1 + \left(\frac{q\varepsilon t}{E_0}\right)^2} - 1 \right) \quad y(t) = \frac{P_{yo}}{q\varepsilon} \sinh^{-1}\left(\frac{q\varepsilon t}{E_0}\right)$$

$$\sinh\left(\frac{q\varepsilon \cdot y}{P_{y_0}}\right) = \frac{q\varepsilon t}{E_0}$$

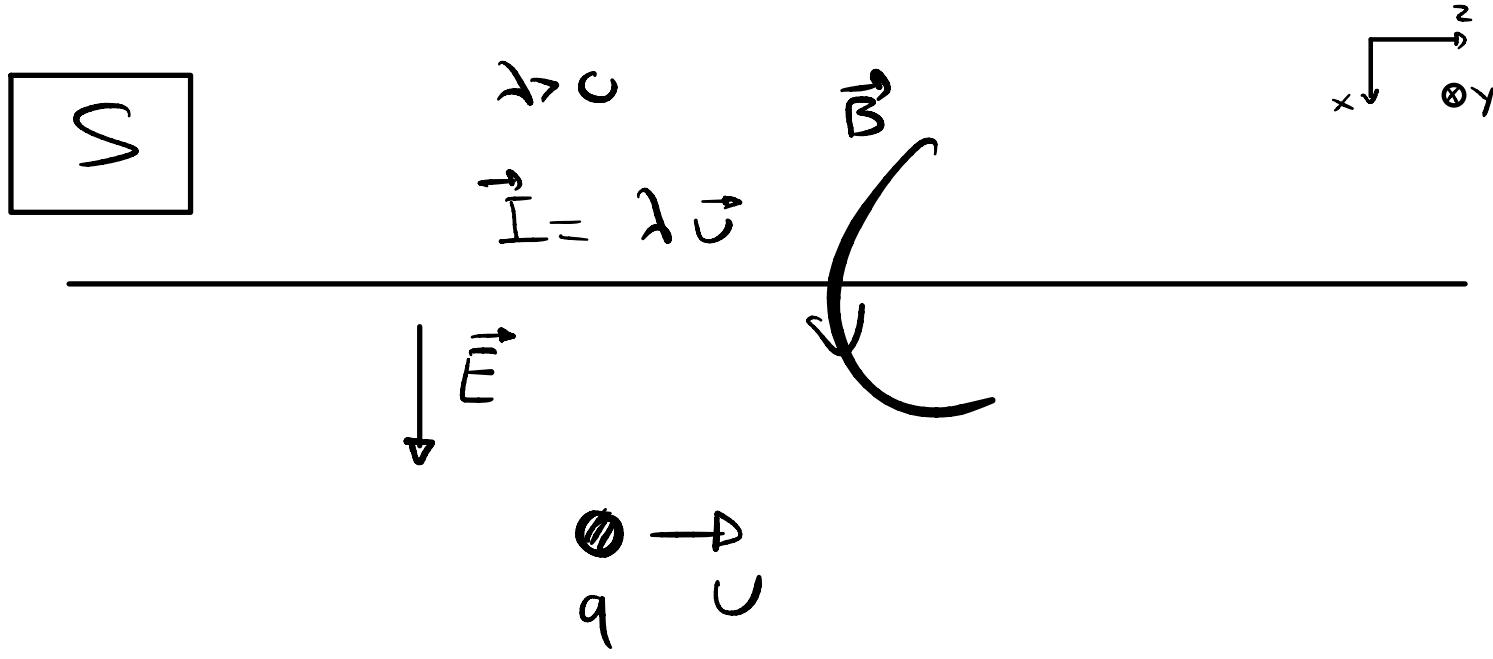
$$x(y) = \frac{E_0}{q\varepsilon} \left(\sqrt{1 + (\sinh(\frac{q\varepsilon \cdot y}{P_{y0}}))^2} - 1 \right)$$

$$x(y) = \frac{E_0}{q\varepsilon} \left[\cosh\left(\frac{q\varepsilon \cdot y}{Py_0}\right) - 1 \right]$$



προβήγκη εξεταστική 30.09.2020

Tupelo 6to e-class



$$\bar{U}' = G$$

A diagram illustrating a sequence of operations or states. The top row consists of ten red plus signs (+). The bottom row consists of fifteen black plus signs (+). A horizontal arrow points from left to right, positioned between the two rows. Below the arrow is the letter c , indicating the direction of progression.